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PATENT

Case Docket No. MNFRAME.044A

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WASHINGTON, D.C. 20231

ATTENTION: APPLICATION BRANCH

Sir:

Transmitted herewith for filing is the patent application of

Inventor(s): Ahmad Nouri and Karl S. Johnson

For: SYSTEM FOR DISPLAYING SYSTEM STATUS


Enclosed are:

- (X) Appendix A attached to the specification.
- (X) Appendix B in 27 pages.
- (X) Twenty-Six (26) sheet(s) of informal drawings.
- (X) UNSIGNED declaration and power of attorney enclosed.
- (X) Return prepaid postcard.

CLAIMS AS FILED

FOR	NUMBER FILED	NUMBER EXTRA	RATE	FEE
Basic Fee			\$790	\$790
Total Claims	13 - 20 =	0 x	\$22	\$0
Independent Claims	1 - 3 =	0 x	\$82	\$0
If application contains any multiple dependent claims(s), then add			\$270	\$0
			TOTAL FILING FEE	\$790

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RJS-3415:cd
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DECLARATION AND POWER OF ATTORNEY - USA PATENT APPLICATION

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name;

I believe I am an original, first and joint inventor of the subject matter which is claimed and for which a patent is sought on the invention entitled SYSTEM FOR DISPLAYING SYSTEM STATUS; the specification of which is attached hereto;

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above;

I acknowledge the duty to disclose information which is material to patentability as defined in Title 37, Code of Federal Regulations, § 1.56;

I hereby claim the benefit under Title 35, United States Codes § 119(e) of any United States provisional application(s) listed below.

Application No.: 60/046,326 Filing Date: May 13, 1997

Application No.: 60/046,397 Filing Date: May 13, 1997

Application No.: 60/047,016 Filing Date: May 13, 1997

Application No.: 60/046,416 Filing Date: May 13, 1997

POWER OF ATTORNEY: I hereby appoint the following attorneys and/or agents to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith (if this application is assigned, I acknowledge that the appointed individuals do not represent me, and that instead they represent the assignee): Louis J. Knobbe, Registration No. 18,780; Don W. Martens, Registration No. 21,107; Gordon H. Olson, Registration No. 20,319; James B. Bear, Registration No. 25,221; Darrell L. Olson, Registration No. 28,247; William B. Bunker, Registration No. 29,365; William H. Nieman, Registration No. 30,201; Lowell Anderson, Registration No. 30,990; Arthur S. Rose, Registration No. 28,038; James F. Lesniak, Registration No. 25,240; Ned A. Israelsen, Registration No. 29,655; Drew S. Hamilton, Registration No. 29,801; Jerry T. Sewell, Registration No. 31,567; John B. Sganga, Jr., Registration No. 31,302; Edward A. Schlatter, Registration No. 32,297; Gerard von Hoffmann, Registration No. 33,043; Joseph R. Re, Registration No. 31,291; John M. Carson, Registration No. 34,303; Andrew H. Simpson, Registration No. 31,469; Daniel E. Altman, Registration No. 34,115; Anita M. Kirkpatrick, Registration No. 32,617; Ernest A. Beutler, Registration No. 19,901; Vito A. Canuso, Registration No. 35,471; William H. Shreve, Registration No. 35,678; Stephen C. Jensen, Registration No. 35,556; Steven J. Nataupsky, Registration No. 37,688; Michael H. Trenholm, Registration No. 37,743; Craig S. Summers, Registration No. 31,430; AnneMarie Kaiser, Registration No. 37,649; Brenton R. Babcock, Registration No. 39,592;

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I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful, false statements may jeopardize the validity of the application or any patent issued thereon.

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RJS-3414:CD
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SYSTEM FOR DISPLAYING SYSTEM STATUSRelated Applications

This application is related to U.S. Application No. _____, entitled
5 "SYSTEM FOR POWERING UP AND POWERING DOWN A SERVER", Attorney
Docket No. MNFRAME.018A; U.S. Application No. _____, entitled "METHOD
OF POWERING UP AND POWERING DOWN A SERVER", Attorney Docket No.
MNFRAME.019A; U.S. Application No. _____, entitled "SYSTEM FOR
10 RESETTING A SERVER", Attorney Docket No. MNFRAME.020A; U.S. Application
No. _____, entitled "METHOD OF RESETTING A SERVER", Attorney Docket
No. MNFRAME.021A; U.S. Application No. _____, entitled "SYSTEM FOR
DISPLAYING FLIGHT RECORDER", Attorney Docket No. MNFRAME.022A; U.S.
Application No. _____, entitled "METHOD OF DISPLAYING FLIGHT
15 RECORDER", Attorney Docket No. MNFRAME.023A; U.S. Application
No. _____, entitled "METHOD OF DISPLAYING SYSTEM STATUS",
Attorney Docket No. MNFRAME.045A, which are being filed concurrently herewith
on October 1, 1997.

Priority Claim

The benefit under 35 U.S.C. § 119(e) of the following U.S. provisional
application(s) is hereby claimed:

	Title	Application No.	Filing Date
25	"Remote Software for Monitoring and Managing Environmental Management System"	60/046,326	May 13, 1997
	"Remote Access and Control of Environmental Management System"	60/046,397	May 13, 1997
30	"Hardware and Software Architecture for Inter-Connecting an Environmental Management System with a Remote Interface"	60/047,016	May 13, 1997

Title	Application No.	Filing Date
"Self Management Protocol for a Fly-By-Wire Service Processor"	60/046,416	May 13, 1997

Appendices

Appendix A, which forms a part of this disclosure, is a list of commonly owned copending U.S. patent applications. Each one of the applications listed in Appendix A is hereby incorporated herein in its entirety by reference thereto.

Appendix B, which forms part of this disclosure, is a copy of the U.S. provisional patent application filed May 13, 1997, entitled "Remote Software for Monitoring and Managing Environmental Management System" and assigned Application No. 60/046,326. Page 1, line 6 of the provisional application has been changed from the original to positively recite that the entire provisional application, including the attached documents, forms part of this disclosure.

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Background of the Invention

Field of the Invention

The present invention relates to fault tolerant computer systems. More specifically, the invention is directed to a system for providing remote access and control of server environmental management.

Description of the Related Technology

As enterprise-class servers become more powerful and more capable, they are also becoming increasingly sophisticated and complex. For many companies, these changes lead to concerns over server reliability and manageability, particularly in light of the increasingly critical role of server-based applications. While in the past many systems administrators were comfortable with all of the various components that made up a standards-based network server, today's generation of servers can appear as an incomprehensible, unmanageable black box. Without visibility into the underlying behavior of the system, the administrator must "fly blind." Too often the only indicators the network manager has on the relative health of a particular server is whether or not it is running.

It is well-acknowledged that there is a lack of reliability and availability of most standards-based servers. Server downtime, resulting either from hardware or software faults or from regular maintenance, continues to be a significant problem. By one estimate, the cost of downtime in mission critical environments has risen to an annual total of \$4.0 billion for U.S. businesses, with the average downtime event resulting in a \$140 thousand loss in the retail industry and a \$450 thousand loss in the securities industry. It has been reported that companies lose as much as \$250 thousand in employee productivity for every 1% of computer downtime. With emerging Internet, intranet and collaborative applications taking on more essential business roles every day, the cost of network server downtime will continue to spiral upward.

While hardware fault tolerance is an important element of an overall high availability architecture, it is only one piece of the puzzle. Studies show that a significant percentage of network server downtime is caused by transient faults in the I/O subsystem. These faults may be due, for example, to the device driver, the adapter card firmware, or hardware which does not properly handle concurrent errors, and often causes servers to crash or hang. The result is hours of downtime per failure, while a system administrator discovers the failure takes some action, and manually reboots the server. In many cases, data volumes on hard disk drives become corrupt and must be repaired when the volume is mounted. A dismount-and-mount cycle may

result from the lack of "hot pluggability" in current standards-based servers. Diagnosing intermittent errors can be a frustrating and time-consuming process. For a system to deliver consistently high availability, it must be resilient to these types of faults. Accurate and available information about such faults is central to diagnosing the underlying problems and taking corrective action.

Modern fault tolerant systems have the functionality to provide the ambient temperature of a storage device enclosure and the operational status of other components such as the cooling fans and power supply. However, a limitation of these server systems is that they do not contain self-managing processes to correct malfunctions. Also, if a malfunction occurs in a typical server, it relies on the operating system software to report, record and manage recovery of the fault. However, many types of faults will prevent such software from carrying out these tasks. For example, a disk drive failure can prevent recording of the fault in a log file on that disk drive. If the system error caused the system to power down, then the system administrator would never know the source of the error.

Traditional systems are lacking in detail and sophistication when notifying system administrators of system malfunctions. System administrators are in need of a graphical user interface for monitoring the health of a network of servers. Administrators need a simple point-and-click interface to evaluate the health of each server in the network. In addition, existing fault tolerant servers rely upon operating system maintained logs for error recording. These systems are not capable of maintaining information when the operating system is inoperable due to a system malfunction. Existing systems do not have a system log for maintaining information when the main computational processors are inoperable or the operating system has crashed.

Another limitation of the typical fault tolerant system is that the control logic for the diagnostic system is associated with a particular processor. Thus, if the environmental control processor malfunctioned, then all diagnostic activity on the computer would cease. In traditional systems, if a controller dedicated to the fan system failed, then all fan activity could cease resulting in overheating and ultimate

failure of the server. What is desired is a way to obtain diagnostic information when the server OS is not operational or even when main power to the server is down.

Existing fault tolerant systems also lack the power to remotely control a particular server, such as powering up and down, resetting, retrieving or updating system status, displaying flight recorder information and so forth. Such control of the server is desired even when the server power is down. For example, if the operating system on the remote machine failed, then a system administrator would have to physically go to the remote machine to re-boot the malfunctioning machine before any system information could be obtained or diagnostics could be started.

Therefore, a need exists for improvements in server management which will result in greater reliability and dependability of operation. Server users are in need of a management system by which the users can accurately gauge the health of their system. Users need a high availability system that must not only be resilient to faults, but must allow for maintenance, modification, and growth--without downtime. System users must be able to replace failed components, and add new functionality, such as new network interfaces, disk interface cards and storage, without impacting existing users. As system demands grow, organizations must frequently expand, or scale, their computing infrastructure, adding new processing power, memory, storage and I/O capacity. With demand for 24-hour access to critical, server-based information resources, planned system downtime for system service or expansion has become unacceptable.

Summary of the Invention

The inventive remote access system provides system administrators with new levels of client/server system availability and management. It gives system administrators and network managers a comprehensive view into the underlying health of the server--in real time, whether on-site or off-site. In the event of a failure, the invention enables the administrator to learn why the system failed, why the system was unable to boot, and to control certain functions of the server from a remote station.

One embodiment of the present invention is a system for retrieving or updating system status for a computer, the system comprising: a first computer; a microcontroller capable of providing a retrieve or update system status signal to the first computer; a remote interface connected to the microcontroller; and a second computer connected to the first computer via the remote interface and communicating a retrieve or update system status command to the microcontroller.

Brief Description of the Drawings

Figure 1 is a top level block diagram of a server system having a microcontroller network in communication with a local client computer or a remote client computer utilized by one embodiment of the present invention.

Figure 2 is a detailed block diagram of the microcontroller network shown in Figure 1.

Figure 3 is a diagram of serial protocol message formats utilized in communications between the client computer and remote interface shown in Figures 1 and 2.

Figures 4a and 4b are one embodiment of a flow diagram of a power-on process performed by the microcontroller network and client computer of Figures 1 and 2.

Figure 5 is one embodiment of a flow diagram of the power-on function shown in Figure 4b.

Figures 6a and 6b are one embodiment of a flow diagram of a power-off process performed by the microcontroller network and client computer of Figures 1 and 2.

Figure 7 is one embodiment of a flow diagram of the power-off function shown in Figure 6b.

Figures 8a and 8b are one embodiment of a flow diagram of a reset process performed by the microcontroller network and client computer of Figures 1 and 2.

Figure 9 is one embodiment of a flow diagram of the reset function shown in Figure 8b.

Figures 10a and 10b are one embodiment of a flow diagram of a display flight recorder process performed by the microcontroller network and client computer of Figures 1 and 2.

5 Figure 11 is one embodiment of a flow diagram of the read non-volatile RAM (NVRAM) contents function shown in Figure 10b.

Figures 12a, 12b and 12c are a detailed block diagram of the microcontroller network components showing a portion of the inputs and outputs of the microcontrollers shown in Figure 2.

10 Figures 13a and 13b are one embodiment of a flow diagram of a system status process performed by the microcontroller network and client computer of Figures 1 and 2.

Figure 14 is one embodiment of a flow diagram of the system status function shown in Figure 13b.

15 Figure 15 is an exemplary screen display of a server power-on window seen at the client computer to control the microcontroller network of Figures 1 and 2.

Figure 16 is an exemplary screen display of a flight recorder window seen at the client computer to control the microcontroller network of Figures 1 and 2.

Figure 17 is an exemplary screen display of a system status window seen at the client computer to control the microcontroller network of Figures 1 and 2.

20 Figure 18 is an exemplary screen display of a system status:fans window seen at the client computer to control the microcontroller network of Figures 1 and 2.

Figure 19 is an exemplary screen display of a system status:fans:canister A window seen at the client computer to control the microcontroller network of Figures 1 and 2.

25

Detailed Description of the Invention

The following detailed description presents a description of certain specific embodiments of the present invention. However, the present invention can be embodied in a multitude of different ways as defined and covered by the claims. In
30 this description, reference is made to the drawings wherein like parts are designated with like numerals throughout.

For convenience, the description will be organized into the following principal sections: Introduction, Server System, Microcontroller Network, Remote Interface Serial Protocol, Power-On Flow, Power-Off Flow, Reset Flow, Flight Recorder Flow, and System Status Flow.

5

I. INTRODUCTION

The inventive computer server system and client computer includes a distributed hardware environment management system that is built as a small self-contained network of microcontrollers. Operating independently of the system processor and operating software, the present invention uses one or more separate
10 processors for providing information and managing the hardware environment that may include fans, power supplies and/or temperature.

One embodiment of the present invention facilitates remotely powering-on and powering-off of the server system by use of a client computer. The client computer
15 may be local to the server system, or may be at a location remote from the server system, in which case a pair of modems are utilized to provide communication between the client computer and the server system. A remote interface board connects to the server and interfaces to the server modem. Recovery manager software is loaded on the client computer to control the power-on and power-off processes and
20 to provide feedback to a user though a graphical user interface.

Another embodiment of the present invention facilitates remotely resetting the server system by use of the client computer. Resetting the server system brings the server and operating system to a normal operating state. Recovery manager software is loaded on the client computer to control the resetting process and to provide
25 feedback to a user though a graphical user interface.

Another embodiment of the present invention provides for a system log, known as a "flight recorder," which records hardware component failure and software crashes in a Non-Volatile RAM. With real time and date referencing, the system recorder enables system administrators to re-construct system activity by accessing the log.
30 This information is very helpful in diagnosing the server system.

Initialization, modification and retrieval of system conditions is performed through utilization of a remote interface by issuing commands to the environmental processors. The system conditions may include system log size, presence of faults in the system log, serial number for each of the environmental processors, serial numbers for each power supply of the system, system identification, system log count, power settings and presence, canister presence, temperature, BUS/CORE speed ratio, fan speeds, settings for fan faults, LCD display, Non-Maskable Interrupt (NMI) request bits, CPU fault summary, FRU status, JTAG enable bit, system log information, remote access password, over-temperature fault, CPU error bits, CPU presence, CPU thermal fault bits, and remote port modem. The aforementioned list of capabilities provided by the present environmental system is not all-inclusive.

The server system and client computer provides mechanisms for the evaluation of the data that the system collects and methods for the diagnosis and repair of server problems in a manner that system errors can be effectively and efficiently managed. The time to evaluate and repair problems is minimized. The server system ensures that the system will not go down, so long as sufficient system resources are available to continue operation, but rather degrade gracefully until the faulty components can be replaced.

II. SERVER SYSTEM

Referring to Figure 1, a server system 100 with a client computer will be described. In one embodiment, the server system hardware environment 100 may be built around a self-contained network of microcontrollers, such as, for example, a remote interface microcontroller on the remote interface board or circuit 104, a system interface microcontroller 106 and a system recorder microcontroller 110. This distributed service processor network 102 may operate as a fully self-contained subsystem within the server system 100, continuously monitoring and managing the physical environment of the machine (e.g., temperature, voltages, fan status). The microcontroller network 102 continues to operate and provides a system administrator with critical system information, regardless of the operational status of the server 100.

Information collected and analyzed by the microcontroller network 102 can be presented to a system administrator using either SNMP-based system management software (not shown), or using microcontroller network Recovery Manager software 130 through a local connection 121 or a dial-in connection 123. The system management software, which interfaces with the operating software (OS) 108 such as Microsoft Windows NT Version 4.0 or Novell Netware Version 4.11, for example, provides the ability to manage the specific characteristics of the server system, including Hot Plug Peripheral Component Interconnect (PCI), power and cooling status, as well as the ability to handle alerts associated with these features when the server is operational.

The microcontroller network Recovery Manager software 130 allows the system administrator to query the status of the server system 100 through the microcontroller network 102, even when the server is down. In addition, the server Operating Software 108 does not need to be running to utilize the Recovery Manager 130. Users of the Recovery Manager 130 are able to manage, diagnose and restore service to the server system quickly in the event of a failure through a friendly graphical user interface (GUI).

Using the microcontroller network remote management capability, a system administrator can use the Recovery Manager 130 to re-start a failed system through a modem connection 123. First, the administrator can remotely view the microcontroller network Flight Recorder, a feature that may, in one embodiment, store all system messages, status and error reports in a circular System Recorder memory. In one embodiment, the System Recorder memory may be a Non-Volatile Random Access Memory buffer (NVRAM) 112. Then, after determining the cause of the system problem, the administrator can use microcontroller network "fly by wire" capability to reset the system, as well as to power the system off or on. "Fly by wire" denotes that no switch, indicator or other control is directly connected to the function it monitors or controls, but instead, all the control and monitoring connections are made by the microcontroller network 102.

The remote interface or remote interface board (RIB) 104 interfaces the server system 100 to an external client computer. The RIB 104 connects to either a local

client computer 122 at the same location as the server 100 or to a remote client computer 124 either directly or through an optional switch 120. The client computer 122/124 may in one embodiment run either Microsoft Windows 95 or Windows NT Workstation version 4.0 operating software (OS) 132. The processor and RAM requirements of the client computer 122/124 are such as may be specified by the vendor of the OS 132. The serial port of the client computer 122/124 may utilize a type 16550A Universal Asynchronous Receiver Transmitter (UART). The switch facilitates either the local connection 121 or the modem connection 123 at any one time, but allows both types of connections to be connected to the switch. In an another embodiment, either the local connection 121 or the modem connection 123 is connected directly to the RIB 104. The local connection 121 utilizes a readily available null-modem serial cable to connect to the local client computer. The modem connection may utilize a Hayes-compatible server modem 126 and a Hayes-compatible client modem 128. In one embodiment, a model fax modem V.34X 33.6K available from Zoom is utilized as the client modem and the server modem. In another embodiment, a Sportster 33.6K fax modem available from US Robotics is utilized as the client modem.

The steps of connecting the remote client computer 124 to the server 100 will now be briefly described. The remote interface 104 has a serial port connector (not shown) that directly connects with a counterpart serial port connector of the external server modem 126 without the use of a cable. If desired, a serial cable could be used to interconnect the remote interface 104 and the server modem 126. The cable end of an AC to DC power adapter (not shown, for example 120 Volt AC / 7.5 Volt DC) is then connected to a DC power connector (not shown) of the remote interface, while the double-prong end is plugged into a 120 Volt AC wall outlet. One end of an RJ-45 parallel-wire data cable 103 is then plugged into an RJ-45 jack (not shown) on the remote interface 104, while the other end is plugged into a RJ-45 Recovery Manager jack on the server 100. The RJ-45 jack on the server then connects to the microcontroller network 102. The server modem 126 is then connected to a communications network 127 using an appropriate connector. The communications network 127 may be a public switched telephone network, although other modem

types and communication networks are envisioned. For example, if cable modems are used for the server modem 126 and client modem 128, the communications network can be a cable television network. As another example, satellite modulator/demodulators can be used in conjunction with a satellite network.

5 In another embodiment, the server modem to client modem connection may be implemented by an Internet connection utilizing the well known TCP/IP protocol. Any of several Internet access devices, such as modems or network interface cards, may be utilized. Thus, the communications network 127 may utilize either circuit or packet switching.

10 At the remote client computer 124, a serial cable (for example, a 25-pin D-shell) 129 is used to interconnect the client modem 128 and the client computer 124. The client modem 128 is then connected to the communications network 127 using an appropriate connector. Each modem is then plugged into an appropriate power source for the modem, such as an AC outlet. At this time, the Recovery Manager
15 software 130 is loaded into the client computer 124, if not already present, and activated.

The steps of connecting the local client computer 122 to the server 100 are similar, but modems are not necessary. The main difference is that the serial port connector of the remote interface 104 connects to a serial port of the local client
20 computer 122 by the null-modem serial cable 121.

III. MICROCONTROLLER NETWORK

In one embodiment, the current invention may include a network of microcontrollers 102 (Figure 1). The microcontrollers may provide functionality for
25 system control, diagnostic routines, self-maintenance control, and event logging processors. A further description of the microcontrollers and microcontroller network is provided in U.S. Patent Application No. _____, entitled "Diagnostic and Managing Distributed Processor System".

Referring to Figure 2, in one embodiment of the invention, the network of
30 microcontrollers 102 includes ten processors. One of the purposes of the microcontroller network 102 is to transfer messages to the other components of the

server system 100. The may processors include: a System Interface controller 106, a CPU A controller 166, a CPU B controller 168, a System Recorder 110, a Chassis controller 170, a Canister A controller 172, a Canister B controller 174, a Canister C controller 176, a Canister D controller 178 and a Remote Interface controller 200.

5 The Remote Interface controller 200 is located on the RIB 104 (Figure 1) which is part of the server system 100, but may be external to a server enclosure. The System Interface controller 106, the CPU A controller 166 and the CPU B controller 168 are located on a system board 150 (also sometimes called a motherboard) in the server 100. Also located on the system board are one or more central processing units
10 (CPUs) or microprocessors 164 and an Industry Standard Architecture (ISA) bus 162 that connects to the System Interface Controller 106. Of course, other buses such as PCI, EISA and Microchannel may be used. The CPU 164 may be any conventional general purpose single-chip or multi-chip microprocessor such as a Pentium®, Pentium® Pro or Pentium® II processor available from Intel Corporation, a SPARC
15 processor available from Sun Microsystems, a MIPS® processor available from Silicon Graphics, Inc., a Power PC® processor available from Motorola, or an ALPHA® processor available from Digital Equipment Corporation. In addition, the CPU 164 may be any conventional special purpose microprocessor such as a digital signal processor or a graphics processor.

20 The System Recorder 110 and Chassis controller 170, along with the System Recorder memory 112 that connects to the System Recorder 110, may be located on a backplane 152 of the server 100. The System Recorder 110 and Chassis controller 170 are the first microcontrollers to power up when server power is applied. The System Recorder 110, the Chassis controller 170 and the Remote Interface
25 microcontroller 200 (on the RIB) are the three microcontrollers that have a bias 5 Volt power supplied to them. If main server power is off, an independent power supply source for the bias 5 Volt power is provided by the RIB 104 (Figure 1). The Canister controllers 172-178 are not considered to be part of the backplane 152 because they are located on separate cards which are removable from the backplane 152.

30 Each of the microcontrollers has a unique system identifier or address. The addresses are as follows in Table 1:

TABLE 1

	<u>Microcontroller</u>	<u>Address</u>
	System Interface controller 106	10
	CPU A controller 166	03
5	CPU B controller 168	04
	System Recorder 110	01
	Chassis controller 170	02
	Canister A controller 172	20
	Canister B controller 174	21
10	Canister C controller 176	22
	Canister D controller 178	23
	Remote Interface controller 200	11

15 The microcontrollers may be Microchip Technologies, Inc. PIC processors in
 one embodiment, although other microcontrollers, such as an 8051 available from
 Intel, an 8751, available from Atmel, or a P80CL580 microprocessor available from
 Philips Semiconductor, could be utilized. The PIC16C74 (Chassis controller 170) and
 PIC16C65 (the other controllers) are members of the PIC16CXX family of high-
 20 performance CMOS, fully-static, EPROM-based 8-bit microcontrollers. The PIC
 controllers have 192 bytes of RAM, in addition to program memory, three
 timer/counters, two capture/compare/Pulse Width Modulation modules and two serial
 ports. The synchronous serial port is configured as a two-wire Inter-Integrated Circuit
 (I²C) bus in one embodiment of the invention. The PIC controllers use a Harvard
 25 architecture in which program and data are accessed from separate memories. This
 improves bandwidth over traditional von Neumann architecture controllers where
 program and data are fetched from the same memory. Separating program and data
 memory further allows instructions to be sized differently than the 8-bit wide data
 word. Instruction opcodes are 14-bit wide making it possible to have all single word
 30 instructions. A 14-bit wide program memory access bus fetches a 14-bit instruction
 in a single cycle.

In one embodiment of the invention, the microcontrollers communicate through an I²C serial bus, also referred to as a microcontroller bus 160. The document "The I²C Bus and How to Use It" (Philips Semiconductor, 1992) is hereby incorporated by reference. The I²C bus is a bidirectional two-wire bus and operates at a 400 kbps rate in the present embodiment. However, other bus structures and protocols could be employed in connection with this invention. For example, the Apple Computer ADB, Universal Serial Bus, IEEE-1394 (Firewire), IEEE-488 (GPIB), RS-485, or Controller Area Network (CAN) could be utilized as the microcontroller bus. Control on the microcontroller bus is distributed. Each microcontroller can be a sender (a master) or a receiver (a slave) and each is interconnected by this bus. A microcontroller directly controls its own resources, and indirectly controls resources of other microcontrollers on the bus.

Here are some of the features of the I²C-bus:

- Two bus lines are utilized: a serial data line (SDA) and a serial clock line (SCL).
- Each device connected to the bus is software addressable by a unique address and simple master/slave relationships exist at all times; masters can operate as master-transmitters or as master-receivers.
- The bus is a true multi-master bus including collision detection and arbitration to prevent data corruption if two or more masters simultaneously initiate data transfer.
- Serial, 8-bit oriented, bidirectional data transfers can be made at up to 400 kbit/second in the fast mode.

Two wires, serial data (SDA) and serial clock (SCL), carry information between the devices connected to the I²C bus. Each device is recognized by a unique address and can operate as either a transmitter or receiver, depending on the function of the device. For example, a memory device connected to the I²C bus could both receive and transmit data. In addition to transmitters and receivers, devices can also be considered as masters or slaves when performing data transfers (see Table 2). A master is the device which initiates a data transfer on the bus and generates the clock

signals to permit that transfer. At that time, any device addressed is considered a slave.

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TABLE 2 Definition of I²C-bus terminology

<u>Term</u>	<u>Description</u>
Transmitter	The device which sends the data to the bus
Receiver	The device which receives the data from the bus
Master	The device which initiates a transfer, generates clock signals and terminates a transfer
Slave	The device addressed by a master
Multi-master	More than one master can attempt to control the bus at the same time without corrupting the message
Arbitration	Procedure to ensure that, if more than one master simultaneously tries to control the bus, only one is allowed to do so and the message is not corrupted
Synchronization	Procedure to synchronize the clock signal of two or more devices

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The I²C-bus is a multi-master bus. This means that more than one device capable of controlling the bus can be connected to it. As masters are usually microcontrollers, consider the case of a data transfer between two microcontrollers connected to the I²C-bus. This highlights the master-slave and receiver-transmitter relationships to be found on the I²C-bus. It should be noted that these relationships are not permanent, but depend on the direction of data transfer at that time. The transfer of data would proceed as follows:

- 1) Suppose microcontroller A wants to send information to microcontroller B:
 - microcontroller A (master), addresses microcontroller B (slave);
 - microcontroller A (master-transmitter), sends data to microcontroller B (slave-receiver);
 - microcontroller A terminates the transfer.

2) If microcontroller A wants to receive information from microcontroller B:

- microcontroller A (master addresses microcontroller B (slave);
- microcontroller A (master-receiver) receives data from microcontroller B (slave-transmitter);
- microcontroller A terminates the transfer.

Even in this situation, the master (microcontroller A) generates the timing and terminates the transfer.

The possibility of connecting more than one microcontroller to the I²C-bus means that more than one master could try to initiate a data transfer at the same time. To avoid the chaos that might ensue from such an event, an arbitration procedure has been developed. This procedure relies on the wired-AND connection of all I²C interfaces to the I²C-bus.

If two or more masters try to put information onto the bus, the first to produce a 'one' when the other produces a 'zero' will lose the arbitration. The clock signals during arbitration are a synchronized combination of the clocks generated by the masters using the wired-AND connection to the SCL line.

Generation of clock signal on the I²C-bus is the responsibility of master devices. Each master microcontroller generates its own clock signals when transferring data on the bus.

The command, diagnostic, monitoring and history functions of the microcontroller network 102 are accessed using a global network memory model in one embodiment. That is, any function may be queried simply by generating a network "read" request targeted at the function's known global network address. In the same fashion, a function may be exercised simply by "writing" to its global network address. Any microcontroller may initiate read/write activity by sending a message on the I²C bus to the microcontroller responsible for the function (which can be determined from the known global address of the function). The network memory model includes typing information as part of the memory addressing information.

Using a network global memory model in one embodiment places relatively modest requirements for the I²C message protocol.

- ▶ All messages conform to the I²C message format including addressing and read/write indication.
- ▶ All I²C messages use seven bit addressing.
- ▶ Any controller can originate (be a Master) or respond (be a Slave).
- 5 ▶ All message transactions consist of I²C "Combined format" messages. This is made up of two back-to-back I²C simple messages with a repeated START condition between (which does not allow for re-arbitrating the bus). The first message is a Write (Master to Slave) and the second message is a Read (Slave to Master).
- 10 ▶ Two types of transactions are used: Memory-Read and Memory-Write.
- ▶ Sub-Addressing formats vary depending on data type being used.

IV. REMOTE INTERFACE SERIAL PROTOCOL

15 The microcontroller network remote interface serial protocol communicates microcontroller network messages across a point-to-point serial link. This link is between the RIB controller 200 that is in communication with the Recovery Manager 130 at the remote client 122/124. This protocol encapsulates microcontroller network messages in a transmission packet to provide error-free communication and link security.

20 In one embodiment, the remote interface serial protocol uses the concept of byte stuffing. This means that certain byte values in the data stream have a particular meaning. If that byte value is transmitted by the underlying application as data, it must be transmitted as a two-byte sequence.

The bytes that have a special meaning in this protocol are:

25	SOM 206	Start of a message
	EOM 216	End of a message
	SUB	The next byte in the data stream must be substituted before processing.
	INT 220	Event Interrupt
30	Data 212	An entire microcontroller network message

As stated above, if any of these byte values occur as data in a message, a two-byte sequence must be substituted for that byte. The sequence is a byte with the value of SUB, followed by a type with the value of the original byte, which is incremented by one. For example, if a SUB byte occurs in a message, it is transmitted as a SUB followed by a byte that has a value of SUB+1.

Referring to Figure 3 the two types of messages 201 used by the remote interface serial protocol will be described.

1. Requests 202, which are sent by remote management (client) computers 122/124 (Figure 1) to the remote interface 104.
2. Responses 204, which are returned to the requester 122/124 by the remote interface 104.

The fields of the messages are defined as follows:

SOM 206	A special data byte value marking the start of a message.
EOM 216	A special data byte value marking the end of a message.
Seq.# 208	A one-byte sequence number, which is incremented on each request. It is stored in the response.
TYPE 210	One of the following types of requests:
IDENTIFY	Requests the remote interface to send back identification information about the system to which it is connected. It also resets the next expected sequence number. Security authorization does not need to be established before the request is issued.
SECURE	Establishes secure authorization on the serial link by checking password security data provided in the message with the microcontroller network password.
UNSECURE	Clears security authorization on the link and attempts to disconnect it. This requires security authorization to have been previously established.
MESSAGE	Passes the data portions of the message to the microcontroller network for execution. The response

one or more events pending. This message can be used to trigger reading events from the remote interface. Events should be read until the return status changes from OK_EVENT to OK.

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V. POWER-ON FLOW

The microcontroller network 102 (Figure 1) performs various system administration tasks, such as, for example, monitoring the signals that come from server control switches, temperature sensors and client computers. By such signals, the microcontroller network 102, for example, turns on or turns off power to the server components, resets the server system, turns the system cooling fans to high, low or off, provides system operating parameters to the Basic Input/Output System (BIOS), transfers power-on self test (POST) events information from the BIOS, and/or sends data to a system display panel and remote computers.

Microcontroller Communication

A microcontroller, such as the remote interface microcontroller 200, handles two primary tasks: Sending and Receiving messages.

20 1. Handling the requests from other microcontrollers:

Incoming messages are handled based on interrupt, where a first byte of an incoming message is the Slave Address which is checked by all controllers connected to the microcontroller bus 160 (Figure 2). Whichever microcontroller has the matched ID would respond with an acknowledgement to the sender controller. The sender then sends one byte of the message type followed by a two byte command ID, low byte first. The next byte of the message defines the length of the data associated with the message. The first byte of the message also specifies whether it is a WRITE or READ command. If it is a WRITE command, the slave controller executes the command with the data provided in the message and sends back a status response at the end of the task. If it is a READ command, the slave controller gathers the requested

information and sends it back as the response. The codes to execute request commands are classified in groups according to the data type to simplify the code.

5 2. Sending a message to other microcontrollers:

10 Messages can be initiated by any controller on the bus 160 (Figure 2). For example, the message can be an event detected by a controller and sent to the System Recorder controller and System Interface controller 106, or it could also be a message from the remote interface 104 (Figure 1) to a specific controller on the bus 160. The sender usually sends the first byte defining the target processor and waits for the acknowledgement, which is the reverse logic from the Receiving a Message sequence. The sender also generates the necessary clock for the communication.

15 Referring to Figures 4a, 4b and Figure 1, a Power-On process 270 will now be described. Process 270 begins at start state 272 and if a connection between the client computer 122/124 and the server 100 is already active, process 270 proceeds to directly to state 296. Otherwise, if a connection is not already active, process 270 proceeds to state 273 and utilizes the Recovery Manager software 130 to present a dialog window to the user on a display of the client computer 122/124 requesting information. The user is requested to enter a password for security purposes. The dialog window also has a pair of radio-buttons to select either a serial (local) connection or a modem (remote) connection. If serial is selected, the user is requested to select a COM port. If modem is selected, the user is requested to enter a telephone number to be used in dialing the server modem.

20 Moving to decision state 274, process 270 determines if a modem-type connection was selected. A modem-type connection is generally utilized in the situation where the client computer 124 is located at a location remote from the server 100. If it is determined at decision state 274 that a modem connection is utilized, process 270 moves to state 276 wherein the client computer 124 is connected to the

client modem 128. Moving to state 278, a connection is established between the client modem 128 and the server modem 126 via a communications network 127, as previously described above. Continuing at state 280, the server modem 126 connects with the remote interface 104. Proceeding to state 282, the remote interface 104 connects to the server 100 via the RJ-45 cable 103. Moving to state 286, the Recovery Manager software 130 at the client computer 124 dials the server modem 126 through the client modem 128, handshakes with the remote interface 104, and checks the previously entered password. Process 270 remains at state 286 until a successful communication path with the remote interface 104 is established.

Returning to decision state 274, if a local connection 121 is utilized instead of the modem connection 123, process 270 proceeds to state 288 wherein the local client computer 122 is connected with the remote interface 104. Moving to state 292, the remote interface 104 is connected with the server 100. The previously entered password (at state 273) is sent to the remote interface 104 to identify the user at the local computer 122. If the password matches a password that is stored in the server system 100, the communication path with the remote interface is enabled.

After successful modem communication has been established and the password confirmed at state 286, or at the completion of connecting the remote interface to the server and checking the password at state 292, process 270 continues at state 296. At state 296, the Recovery Manager software 130 will in one embodiment display a recovery manager window 920, which includes a server icon 922 as shown in Figure 15. A server window panel 928 and a confirmation dialog box 936 are not displayed at this time. The user at the client computer 122/124 then selects the server icon on the display, such as, for example by clicking a pointer device on the icon. Moving to state 298, the server window panel 928 is then displayed to the user. The user confirmation box 936 is not displayed at this time. The user selects a Power On button 930 on the window panel 928 to trigger the power-on operation. Continuing at state 300, the user confirmation dialog box 936 is then displayed on the client computer display. If the user confirms that the server is to be powered up, process 270 proceeds through off page connector A 302 to state 304 on Figure 4b.

At state 304, the Recovery Manager software 130 at the client computer 122/124 provides a microcontroller network command (based on selecting the Power On button) and sends it to communication layer software. Proceeding to state 306, the communication layer puts a communications protocol around the command (from state 304) and sends the encapsulated command to the server through the client modem 128, the server modem 126 and the remote interface 104. The communications protocol was discussed in conjunction with Figure 3 above. The encapsulated command is of the Request type 202 shown in Figure 3. The remote interface 104 converts the encapsulated command to the microcontroller network format, which is described in U.S. Patent Application No. _____, entitled "DIAGNOSTIC AND MANAGING DISTRIBUTED PROCESSOR SYSTEM," and in U.S. Patent Application No. _____, entitled "SYSTEM ARCHITECTURE FOR REMOTE ACCESS AND CONTROL OF ENVIRONMENTAL MANAGEMENT." Process 270 then continues to a function 310 wherein the server receives the command and powers on the server. Function 310 will be further described in conjunction with Figure 5.

Moving to state 312, the response generated by the server is then sent to the remote interface 104. In one embodiment, the microcontroller (the Chassis controller 170 in this instance) performing the command at the server returns status at the time of initiation of communication with the microcontroller. At the completion of the power-on operation by the Chassis controller 170, the Recovery Manager 130 sends a read status command to the Chassis controller (using states 304 and 306) to retrieve information on the results of the operation.

Proceeding to decision state 314, process 270 determines if the power on command was successful. If so, process 270 proceeds to state 316 wherein the remote interface 104 sends the response to the server modem 126 indicating the success of the command. Alternatively, if a local connection 121 is utilized, the response is sent to the local client computer 122. However, if the power on is not successful, as determined at decision state 314, process 270 proceeds to state 318 wherein the remote interface 104 sends the response to the server modem (or local client computer) indicating a failure of the command. At the conclusion of either state 316 or 318,

process 270 proceeds to state 320 wherein the remote interface 104 sends the response back through the server modem 126 to the client modem 128. Moving to state 322, the client modem 128 sends the response back to the Recovery Manager software 130 at the remote client computer 124. Note that if the local connection 121 is being utilized, states 320 and 322 are not necessary. Proceeding to decision state 324, process 270 determines whether the command was successful. If so, process 270 continues at state 326 and displays a result window showing the success of the command on the display at the client computer 122/124. However, if the command was not successful, process 270 proceeds to state 328 wherein a result window showing failure of the command is displayed to the user. Moving to state 330, the details of the command information are available, if the user so desires, by selecting a details button. At the completion of state 326 or state 330, process 270 completes at end state 332.

Referring to Figure 5, one embodiment of the server Power On function 310 will now be described. Beginning at start state 360, function 310 proceeds to state 362 and logs the requested power-on to the server 100 in the System Recorder memory 112. Proceeding to decision state 364, function 310 determines if a system over-temperature condition is set. If so, function 310 proceeds to state 366 and sends a over-temperature message to the remote interface 104. Advancing to state 368, because the system over-temperature condition is set, the power-on process is stopped and function 310 returns at a return state 370.

Returning to decision state 364, if the system over-temperature condition is not set, function 310 proceeds to state 372 and sets an internal power-on indicator and a reset/run countdown timer. In one embodiment, the reset/run countdown timer is set to a value of five. Advancing to state 374, function 310 turns on the power and cooling fans for the server system board 150, backplane 152 and I/O canisters. The microcontroller network holds the main system processor reset/run control line in the reset state until the reset/run countdown timer expires to allow the system power to stabilize. When the timer expires then the reset/run control is set to "run" and the system processor(s) begin their startup sequence by proceeding to state 376 and calling a BIOS Power-On Self Test (POST) routine. Moving to state 378, the BIOS

initializes a PCI-ISA bridge and a microcontroller network driver. Continuing to state 380, the microcontroller network software monitors: hardware temperatures, switches on a control panel on the server, and signals from the remote interface 104. In one embodiment, state 380 may be performed anywhere during states 376 to 394 because the BIOS operations are performed by the server CPUs 164 (Figure 2) independently of the microcontroller network 102. Function 310 then moves to a BIOS POST Coldstart function 386. In the Coldstart POST function, approximately 61 BIOS subroutines are called. The major groups of the Coldstart path include: CPU initialization, DMA/timer reset, BIOS image check, chipset initialization, CPU register initialization, CMOS test, PCI initialization, extended memory check, cache enable, and message display.

At the completion of the BIOS POST Coldstart function 386, function 310 proceeds to state 388 where BIOS POST events are logged in the System Recorder memory 112. Proceeding to state 390, the BIOS POST performs server port initialization. Continuing at state 392, the BIOS POST initializes the Operating System related controllers (e.g., floppy controller, hard disk controller) and builds a multi-processor table. Advancing to state 394, the BIOS POST performs an OS boot preparation sequence. Function 310 ends at a return state 398.

20 VI. POWER-OFF FLOW

Referring to Figures 6a, 6b and Figure 1, one embodiment of a Power-Off process 420 will now be described. Process 420 begins at start state 422 and if a connection between the client computer 122/124 and the server 100 is already active, process 420 proceeds to directly to state 446. Otherwise, if a connection is not already active, process 420 proceeds to state 423 and utilizes the Recovery Manager software 130 to present a dialog window to the user on a display of the client computer 122/124 requesting information. The user is requested to enter a password for security purposes. The dialog window also has a pair of radio-buttons to select either a serial (local) connection or a modem (remote) connection. If serial is selected, the user is requested to select a COM port. If modem is selected, the user is requested to enter a telephone number to be used in dialing the server modem.

Moving to decision state 424, process 420 determines if the modem-type connection 123 will be utilized. The modem-type connection is generally utilized in the situation where the client computer 124 is located at a location remote from the server 100. If it is determined at decision state 424 that a modem connection is utilized, process 420 moves to state 426 wherein the client computer 124 is connected to the client modem 128. Moving to state 428, a connection is established between the client modem 128 and the server modem 126 via the communications network 127. Continuing at state 430, the server modem 126 connects with the remote interface 104. Proceeding to state 432, the remote interface 104 connects to the server 100 via the RJ-45 cable 103. Moving to state 436, the Recovery Manager software 130 at the client computer 124 dials the server modem 126 through the client modem 128, handshakes with the remote interface 104, and checks the previously entered password. Process 420 remains at state 436 until a successful communication path with the remote interface 104 is established.

Returning to decision state 424, if the local connection 121 is utilized instead of the modem connection 123, process 420 proceeds to state 438 wherein the local client computer 122 is connected with the remote interface 104. Moving to state 442, the remote interface 104 is connected with the server 100. The previously entered password (at state 423) is sent to the remote interface 104 to identify the user at the local computer 122. If the password matches the password that is stored in the server system 100, the communication path with the remote interface 104 is enabled.

After successful modem communication has been established and the password confirmed at state 436, or at the completion of checking the password at state 442, process 420 continues at state 446. At state 446, the Recovery Manager software 130 will in one embodiment display the Recovery Manager window 920, which includes the server icon 922 as shown in Figure 15. The server window panel 928 and the confirmation dialog box 936 are not displayed at this time. The user at the client computer 122/124 then selects the server icon 922 on the display, such as by clicking the pointer device on the icon. Moving to state 448, the server window panel 928 (Figure 15) is then displayed to the user. The user selects a Power Off button 932 on the window panel 928 to trigger the power-off operation. Continuing at state 450, a

user confirmation dialog box is then displayed on the client computer display. If the user confirms that the server is to be powered down, process 420 proceeds through off page connector A 452 to state 454 on Figure 6b.

At state 454, the Recovery Manager software 130 at the client computer 122/124 provides a microcontroller network command (based on selecting the Power Off button) and sends it to communication layer software. Proceeding to state 456, the communication layer puts a communications protocol around the command (from state 454) and sends the encapsulated command to the server through the client modem 128, the server modem 126 and the remote interface 104. The encapsulated command is of the Request type 202 shown in Figure 3. Process 420 then continues to a function 460 wherein the server receives the command and powers off the server. Function 460 will be further described in conjunction with Figure 7.

Moving to state 462, the response generated by the server is then sent to the remote interface 104. In one embodiment, the microcontroller (the Chassis controller 170 in this instance) performing the command at the server returns status at the time of initiation of communication with the microcontroller. At the completion of the power-off operation by the Chassis controller 170, the Recovery Manager 130 sends a read status command to the Chassis controller (using states 454 and 456) to retrieve information on the results of the operation.

Proceeding to decision state 464, process 420 determines if the power off command was successful. If so, process 420 proceeds to state 466 wherein the remote interface 104 sends the response to the server modem 126 indicating the success of the command. Alternatively, if a local connection 121 is utilized, the response is sent to the local client computer 122. However, if the power off is not successful, as determined at decision state 464, process 270 proceeds to state 468 wherein the remote interface 104 sends the response to the server modem (or local client computer) indicating a failure of the command. At the conclusion of either state 466 or 468, process 420 proceeds to state 470 wherein the remote interface 104 sends the response back through the server modem 126 to the client modem 128. Moving to state 472, the client modem 128 sends the response back to the Recovery Manager software 130 at the remote client computer 124. Note that if the local connection 121 is being

utilized, states 470 and 472 are not necessary. Proceeding to decision state 474, process 420 determines whether the command was successful. If so, process 420 continues at state 476 and displays a result window showing the success of the command on the display at the client computer 122/124. However, if the command was not successful, process 420 proceeds to state 478 wherein a result window showing failure of the command is displayed to the user. Moving to state 480, the details of the command information are available, if the user so desires, by selecting a details button. At the completion of state 476 or state 480, process 420 completes at end state 482.

Referring to Figure 7, the server Power-Off function 460 will now be described. Beginning at start state 500, function 460 proceeds to state 502 and logs the requested Power-Off message in the System Recorder memory 112 (Figure 2) by use of the System Recorder controller 110. Moving to state 504, function 460 clears a system run indicator and clears the reset/run countdown timer. Moving to state 506, function 460 clears an internal power-on indicator. In one embodiment, the power-on indicator is stored by a variable "S4_power_on". Function 460 utilizes the CPU A controller 166 for state 504 and the Chassis controller 170 for state 506. Continuing at state 508, function 460 turns off the power and the cooling fans for the system board 150, the backplane 152 and the canister(s) associated with the Canister controllers 172-178. Function 460 ends at a return state 512.

VII. RESET FLOW

Referring to Figures 8a, 8b and Figure 1, one embodiment of a Reset process 540 will now be described. Process 540 begins at start state 542 and if a connection between the client computer 122/124 and the server 100 is already active, process 540 proceeds to directly to state 566. Otherwise, if a connection is not already active, process 540 proceeds to state 543 and utilizes the Recovery Manager software 130 to present a dialog window to the user on a display of the client computer 122/124 requesting information. The user is requested to enter a password for security purposes. The dialog window also has a pair of radio-buttons to select either a serial (local) connection or a modem (remote) connection. If serial is selected, the user is

requested to select a COM port. If modem is selected, the user is requested to enter a telephone number to be used in dialing the server modem.

Moving to decision state 544, process 540 determines if the modem-type connection 123 was selected. The modem-type connection is generally utilized in the situation where the client computer 124 is located at a location remote from the server 100. If it is determined at decision state 544 that a modem connection is utilized, process 540 moves to state 546 wherein the client computer 124 is connected to the client modem 128. Moving to state 548, a connection is established between the client modem 128 and the server modem 126 via the communications network 127. Continuing at state 550, the server modem 126 connects with the remote interface 104. Proceeding to state 552, the remote interface 104 connects to the server 100 via the RJ-45 cable 103. Moving to state 556, the Recovery Manager software 130 at the client computer 124 dials the server modem 126 through the client modem 128, handshakes with the remote interface 104, and checks the previously entered password. Process 540 remains at state 556 until a successful communication path with the remote interface 104 is established.

Returning to decision state 544, if the local connection 121 is utilized instead of the modem connection 123, process 540 proceeds to state 558 wherein the local client computer 122 is connected with the remote interface 104. Moving to state 562, the remote interface 104 is connected with the server 100. The password previously entered (at state 543) is sent to the remote interface 104 to identify the user at the local computer 122. If the password matches the password that is stored in the server system 100, the communication path with the remote interface 104 is enabled.

After successful modem communication has been established and the password confirmed at state 556, or at the completion of connecting the remote interface to the server and checking the password at state 562, process 540 continues at state 566. At state 566, the Recovery Manager software 130 will in one embodiment display the Recovery Manager window 920, which includes the server icon 922 as shown in Figure 15. The server window panel 928 and the confirmation dialog box 936 are not displayed at this time. The user at the client computer 122/124 then selects the server icon 922 on the display, such as by clicking the pointer device on the icon. Moving

to state 568, the server window panel 928 (Figure 15) is then displayed to the user. The user confirmation box 936 is not displayed at this time. The user selects a System Reset button 934 on the window panel 928 to trigger the System Reset operation. Continuing at state 570, a user confirmation dialog box is then displayed on the client computer display. If the user confirms that the system is to be reset, process 540 proceeds through off page connector A 572 to decision state 574 on Figure 8b.

At decision state 574, process 540 determines if the server is currently running (powered up, such as after a power on command has been issued). If not, process 540 continues to state 576 wherein a warning message that the server must be running to execute a system reset is displayed on the client computer display to the user. After the warning has been displayed, process 540 moves to end state 578 to terminate the reset process. However, if the server is running, as determined at decision state 574, process 540 proceeds to state 580.

At state 580, the Recovery Manager software 130 at the client computer 122/124 provides a microcontroller network command (based on selecting the System Reset button) and sends it to the communication layer software. Proceeding to state 582, the communication layer puts a communications protocol around the command (from state 580) and sends the encapsulated command to the server through the client modem 128, the server modem 126 and the remote interface 104. The encapsulated command is of the Request type 202 shown in Figure 3. Process 540 then continues to a function 590 wherein the server receives the command and resets the server. Function 590 will be further described in conjunction with Figure 9.

Moving to state 592, the response generated by the server is then sent to the remote interface 104. In one embodiment, the microcontroller (the CPU A controller 166 in this instance) performing the command at the server returns status at the time of initiation of communication with the microcontroller. At the completion of the reset operation by the CPU A controller 166, the Recovery Manager 130 sends a read status command to the CPU A controller (using states 580 and 582) to retrieve information on the results of the operation.

Proceeding to decision state 594, process 540 determines if the system reset command was successful. If so, process 540 proceeds to state 596 wherein the remote interface 104 sends the response to the server modem 126 indicating the success of the command. Alternatively, if a local connection 121 is utilized, the response is sent to the local client computer 122. However, if the system reset is not successful, as determined at decision state 594, process 540 proceeds to state 598 wherein the remote interface 104 sends the response to the server modem (or local client computer) indicating a failure of the command. At the conclusion of either state 596 or 598, process 540 proceeds to state 600 wherein the remote interface 104 sends the response back through the server modem 126 to the client modem 128. Moving to state 602, the client modem 128 sends the response back to the Recovery Manager software 130 at the remote client computer 124. Note that if the local connection 121 is being utilized, states 600 and 602 are not necessary. Proceeding to decision state 604, process 540 determines whether the command was successful. If so, process 540 continues at state 606 and displays a result window showing the success of the command on the display at the client computer 122/124. However, if the command was not successful, process 540 proceeds to state 608 wherein a result window showing failure of the command is displayed to the user. Moving to state 610, the details of the command information are available, if the user so desires, by selecting a details button. At the completion of state 606 or state 610, process 540 completes at end state 612.

Referring to Figure 9, the server reset function 590 will now be described. Beginning at start state 630, function 590 proceeds to the BIOS POST Warmstart function 384. In the Warmstart function 384, approximately 41 subroutines are called. These include the general operations of: reset flag, DMA/timer reset, chipset initialization, CMOS test, PCI initialization, cache enable, and message display. At the completion of the BIOS POST Warmstart function 384, function 590 proceeds to state 388 where BIOS POST events are logged in the System Recorder memory 112. Proceeding to state 390, the BIOS POST performs server port initialization. Continuing at state 392, the BIOS POST initializes the Operating System related controllers (e.g., floppy disk controller, hard disk controller) and builds a multi-

processor table. Advancing to state 394, the BIOS POST performs an OS boot preparation sequence. Moving to state 632, the BIOS initiates an OS boot sequence to bring the operating software to an operational state. Function 590 ends at a return state 636.

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VIII. FLIGHT RECORDER FLOW

A Flight Recorder, which includes the System Recorder controller 110 and the System Recorder memory 112, provides a subsystem for recording a time-stamped history of events leading up to a failure in server system 100. The System Recorder memory 112 may also store identification of components of the server system. In one embodiment, the System Recorder 110 is the only controller which does not initiate messages to other controllers. The System Recorder 110 receives event log information from other controllers and stores the data into the System Recorder memory 112. Upon request, the System Recorder 110 can send a portion and/or the entire logged data to a requesting controller. The System Recorder 110 puts a time stamp from a real-time clock with the data that is saved.

Referring to Figures 10a, 10b and Figure 1, one embodiment of a Display Flight Recorder process 670 will now be described. Process 670 begins at start state 672 and if a connection between the client computer 122/124 and the server 100 is already active, process 670 proceeds to directly to state 696. Otherwise, if a connection is not already active, process 670 proceeds to state 673 and utilizes the Recovery Manager software 130 to present a dialog window to the user on a display of the client computer 122/124 requesting information. The user is requested to enter a password for security purposes. The dialog window also has a pair of radio-buttons to select either a serial (local) connection or a modem (remote) connection. If serial is selected, the user is requested to select a COM port. If modem is selected, the user is requested to enter a telephone number to be used in dialing the server modem.

Moving to decision state 674, process 670 determines if the modem-type connection 123 was selected. The modem-type connection is generally utilized in the situation where the client computer 124 is located at a location remote from the server 100. If it is determined at decision state 674 that a modem connection is utilized,

process 670 moves to state 676 wherein the client computer 124 is connected to the client modem 128. Moving to state 678, a connection is established between the client modem 128 and the server modem 126 via the communications network 127. Continuing at state 680, the server modem 126 connects with the remote interface 104. Proceeding to state 682, the remote interface 104 connects to the server 100 via the RJ-45 cable 103. Moving to state 686, the Recovery Manager software 130 at the client computer 124 dials the server modem 126 through the client modem 128, handshakes with the remote interface 104, and checks the previously entered password. Process 670 remains at state 686 until a successful communication path with the remote interface 104 is established.

Returning to decision state 674, if the local connection 121 is utilized instead of the modem connection 123, process 670 proceeds to state 688 wherein the local client computer 122 is connected with the remote interface 104. Moving to state 692, the remote interface 104 is connected with the server 100. The previously entered password (at state 673) is sent to the remote interface 104 to identify the user at the local computer 122. If the password matches the password that is stored in the server system 100, the communication path with the remote interface 104 is enabled.

After successful modem communication has been established and the password confirmed at state 686, or at the completion of connecting the remote interface to the server and checking the password at state 692, process 670 continues at state 696. At state 696, the Recovery Manager software 130 will in one embodiment display a Recovery Manager window 940, which includes a Flight Recorder icon 942 as shown in Figure 16. A Flight Recorder window panel 944 is not displayed at this time. The user at the client computer 122/124 then selects the Flight Recorder icon 942 on the display, such as by clicking the pointer device on the icon. Moving to state 698, the Flight Recorder window panel 944 (Figure 16) is then displayed to the user. The user selects a Download button 954 on the window panel 944 to trigger the display of the Flight Recorder operation. Note that other options in the Flight Recorder window panel 944 include a Save button 956 for saving a downloaded Flight Recorder (system log or System Recorder memory 112, Figure 1) and a Print button 958 for printing the downloaded Flight Recorder. Continuing at state 700, a user confirmation dialog box

(not shown) is then displayed on the client computer display showing a number of messages in the server system log. Moving to state 702, if the user selects the "OK" button, process 670 displays a progress window of downloaded messages. Process 670 proceeds through off page connector A 703 to state 704 on Figure 10b.

5 At state 704, the Recovery Manager software 130 at the client computer 122/124 provides a microcontroller network command (based on selecting the Download Flight Recorder button 954) and sends it to the communication layer software. Proceeding to state 706, the communication layer puts a communications protocol around the command (from state 704) and sends the encapsulated command
10 to the server through the client modem 128, the server modem 126 and the remote interface 104. The encapsulated command is of the Request type 202 shown in Figure 3. Process 670 then continues to a function 710 wherein the server receives the command and reads the contents of the System Recorder memory 112 (Figure 1). In one embodiment, each read request generates one response such that the Recovery
15 Manager 130 generates multiple read requests to read the complete system log. The server generates one log response during function 710. Function 710 will be further described in conjunction with Figure 11.

 Moving to state 712, each of the responses generated by the server are then sent one at a time to the remote interface 104. Process 670 then proceeds to state 714
20 wherein the remote interface 104 sends each response back through the server modem 126 to the client modem 128. Alternatively, if a local connection 121 is utilized, each response is sent directly to the local client computer 122. Moving to state 716, the client modem 128 sends the response back to the Recovery Manager software 130 at the remote client computer 124. Note that if the local connection 121 is being
25 utilized, state 716 is not necessary. Proceeding to decision state 718, process 670 determines whether the entire download of the Flight Recorder was successful by checking for an end of system log messages status. If so, process 670 continues at state 720 wherein the Recovery Manager 130 (Figure 1) displays (and optionally stores) all messages in the Flight Recorder window panel 944 on the display at the
30 client computer 122/124. However, if the entire download was not successful, process 670 proceeds to state 722 wherein the Recovery Manager 130 displays (and optionally

stores) all messages that were received by the Recovery Manager 120 in the Flight Recorder window panel 944. At the completion of state 720 or state 722, process 670 completes at end state 724.

In one embodiment, the Flight Recorder window panel 944 includes four fields:

5 Time Stamp 946, Severity 948, Message Source 950, and Message 952. Each message in the system log 112 includes a time stamp 946 of when the item was written to the log 112. The time stamp includes the date and the local time zone of the client computer 122/124 running the Recovery Manager 130. In one embodiment, the time stamp information is generated by a timer chip 760 (Figure 12a). The

10 Severity field 948 includes a severity value selected from: unknown, informational, warning, error, and severe/fatal. The Message Source field 950 includes a source selected from: microcontroller network internal, onboard diagnostics, external diagnostics, BIOS, time synchronizer, Windows®, WindowsNT®, NetWare, OS/2, UNIX, and VAX/VMS. The messages in the Message field 952 correspond to the

15 data returned by the controllers on the microcontroller network 102. The controller message data is used to access a set of Message tables associated with the Recovery Manager 130 on the client computer 122/124 to generate the information displayed in the Message field 952. The Message tables include a microcontroller network (wire services) table, a BIOS table and a diagnostics table. An exemplary message from the

20 microcontroller network table includes "temperature sensor #5 exceeds warning threshold". An exemplary message from the BIOS table includes "check video configuration against CMOS". An exemplary message from the diagnostics table includes "correctable memory error".

Referring to Figure 11, the Read NVRAM Contents function 710 will now be

25 described. Beginning at start state 740, function 710 proceeds to state 742 and loads a block log pointer. The System Recorder memory or NVRAM 112 (Figure 2) has two 64K byte memory blocks. The first block is a memory block which stores ID codes of the devices installed in the network. Hence, a command addressed to the first block is typically generated by a controller responsible for updating the presence

30 or absence of devices in the network. The second block of the memory 112 is a memory block that stores event messages in connection with events occurring in the

network. Hence, controllers addressing the second block do so to add entries to the system log or to read previous entries contained in the system log. The System Recorder uses log address pointers to determine where the next new entry in the log should be placed and also to determine where the log is currently being read from. A further description of the System Recorder 110 and the NVRAM 112 is provided in U.S. Patent Application No. _____, entitled, "BLACK BOX RECORDER FOR INFORMATION SYSTEM EVENTS".

Moving to state 744, function 710 reads the log message as addressed by the log pointer. Proceeding to state 746, function 710 returns the log message to the requestor on the microcontroller bus 160 (Figure 2), which is the remote interface controller 200 in this situation. In one embodiment, the remote interface 104 stores the message in a memory 762 (Figure 12c) on the RIB. Proceeding to state 748, process 710 increments the log pointer to point to the next address in the NVRAM block. Continuing at decision state 750, function 710 determines if the end of the messages in the System Recorder memory block has been reached. If not, function 710 proceeds to a normal return state 752. If the end of the messages has been reached, as determined at decision state 750, function 710 moves to a return state 754 and returns a End of Messages status. The Recovery Manager 130 utilizes this status information to stop sending requests to read the System Recorder memory 112.

IX. SYSTEM STATUS FLOW

Figures 12a, 12b and 12c are a detailed block diagram of the microcontroller network components showing specific inputs and outputs of the microcontrollers. An I/O Canister card 758 has fan speed detection circuitry 765 to provide fan speed information to the Canister controller 172 through a fan multiplexer 767. The CPU A controller 166 receives fan speed information from fan speed detection circuitry 764 through a fan multiplexer 765.

Referring to Figures 13a, 13b and Figure 1, one embodiment of a System Status process 770 will now be described. Process 770 begins at start state 772 and if a connection between the client computer 122/124 and the server 100 is already active, process 770 proceeds to directly to state 796. Otherwise, if a connection is not

already active, process 770 proceeds to state 773 and utilizes the Recovery Manager software 130 to present a dialog window to the user on a display of the client computer 122/124 requesting information. The user is requested to enter a password for security purposes. The dialog window also has a pair of radio-buttons to select
 5 either a serial (local) connection or a modem (remote) connection. If serial is selected, the user is requested to select a COM port. If modem is selected, the user is requested to enter a telephone number to be used in dialing the server modem.

Moving to decision state 774, process 770 determines if the modem-type connection 123 was selected. The modem-type connection is generally utilized in the
 10 situation where the client computer 124 is located at a location remote from the server 100. If it is determined at decision state 774 that a modem connection is utilized, process 770 moves to state 776 wherein the client computer 124 is connected to the client modem 128. Moving to state 778, a connection is established between the client modem 128 and the server modem 126 via the communications network 127.
 15 Continuing at state 780, the server modem 126 connects with the remote interface 104. Proceeding to state 782, the remote interface 104 connects to the server 100 via the RJ-45 cable 103. Moving to state 786, the Recovery Manager software 130 at the client computer 124 dials the server modem 126 through the client modem 128, handshakes with the remote interface 104, and checks the previously entered
 20 password. Process 770 remains at state 786 until a successful communication path with the remote interface 104 is established.

Returning to decision state 774, if the local connection 121 is utilized instead of the modem connection 123, process 770 proceeds to state 788 wherein the local client computer 122 is connected with the remote interface 104. Moving to state 792,
 25 the remote interface 104 is connected with the server 100. The previously entered password (at state 773) is sent to the remote interface 104 to identify the user at the local computer 122. If the password matches the password that is stored in the server system 100, the communication path with the remote interface 104 is enabled.

After successful modem communication has been established and the password confirmed at state 786, or at the completion of connecting the remote interface to the
 30 server and checking the password at state 792, process 770 continues at state 796. At

state 796, the Recovery Manager software 130 will in one embodiment display a Recovery Manager window 960, which includes a System Status icon 970 as shown in Figure 17. A System Status window panel 962 is not displayed at this time. The user at the client computer 122/124 then selects the System Status icon 970 on the display, such as by clicking the pointer device on the icon. Moving to state 798, the System Status window panel 962 (Figure 17) is then displayed to the user. The user selects one of a multiple set of component icons 972-984 on the window panel 962 to initiate a System Status operation. In one embodiment, icon 972 is for Power Supplies, icon 974 is for Temperatures, icon 976 is for Fans, icon 978 is for Processor, icon 980 is for I/O Canisters, icon 982 is for Serial Numbers and icon 984 is for Revisions. When the user selects one of the icons 972-984, the Recovery Manager 130 displays a component window panel to the user, such as exemplary Fans window panel 994 (Figure 18) if the user selected the Fans icon 976.

In one embodiment, the exemplary Fans window panel 994 (Figure 18) includes several fields 985-991: field 985 is for Fan Location, field 986 is for Fan Number within the Location, field 987 is for Fan Speed (rpm, as detected by the microcontrollers 166 and 172 (Figure 12)), field 988 is for Fan Speed Control (high or low), field 989 is for Fault Indicator LED (on or off), field 990 is for Fan Fault (yes or no), and field 991 is for Fan Low-speed Fault Threshold Speed (rpm). Note that this exemplary Fans window panel 994 includes a Refresh button 992 which triggers a retrieval of new values for the fields of the panel.

If the user selects a Canister A icon 1000 in the Recovery Manager window panel 960, the Recovery Manager 130 displays an exemplary Fans detail window panel 1002 (Figure 19). This exemplary panel 1002 provides status information for the fans of the selected Canister A, which in this embodiment includes a status box 1004 for a Fan 1 and a status box 1006 for Fan 2 along with a Canister Present indicator 1008 and a Fault Indicator Led box 1010. These status items 1004-1010 are refreshed (new status information is retrieved) if the user selects a Refresh button 1012. A Fan Low-speed Fault Threshold Speed entry box 1020 and a Fan Speed Control radio button box 1022 allow the user to enter new values if it desired to

change the current settings. An Update operation to change the values of the settings is initiated if the user selects the Update button 1024.

Continuing in Figure 13a at decision state 799, process 770 determines if the Refresh Status operation is to be performed, if for example, the user selected a Refresh button on one of the System status windows. If so, process 770 proceeds to state 800 and initiates the Refresh operation to retrieve new status information for display to the user. If the Refresh operation is not selected, as determined at decision state 799, process 770 advances to decision state 801 to determine if the Update operation is to be performed, if for example, the user selected a Update button on one of the System status windows. If so, process 770 proceeds to state 802 and initiates the Update operation to update item settings that the user desires to change. At the completion of either state 800 or state 802, or if the user selects another status option (e.g., Help), process 670 proceeds through off page connector A 803 to state 804 on Figure 13b.

At state 804, the Recovery Manager software 130 at the client computer 122/124 provides a microcontroller network command (based on selecting one of System Status operations (e.g., Update, Refresh)) and sends it to the communication layer software. Proceeding to state 806, the communication layer puts a communications protocol around the command (from state 804) and sends the encapsulated command to the server through the client modem 128, the server modem 126 and the remote interface 104. The encapsulated command is of the Request type 202 shown in Figure 3. Process 770 then continues to a function 810 wherein the server receives the command and retrieves or updates the selected status information for the selected item(s), e.g., Fans. In one embodiment, for example, each Refresh request generates one response such that the Recovery Manager 130 generates multiple Refresh requests to retrieve the complete set of status information. Function 810 will be further described in conjunction with Figure 14.

Moving to state 812, each of the responses generated by the server are then sent one at a time to the remote interface 104. Process 770 then proceeds to state 814 wherein the remote interface 104 sends each response back through the server modem 126 to the client modem 128. Alternatively, if a local connection 121 is utilized, each

response is sent directly to the local client computer 122. Moving to state 822, the client modem 128 sends the response back to the Recovery Manager software 130 at the remote client computer 124. Proceeding to decision state 824, process 770 determines whether the executed command was a Retrieve (Refresh) or Update command. If the command was a Retrieve, process 770 moves to decision state 826 to determine if the Retrieve operation was successful. If so, process 770 continues to state 828 wherein the Recovery Manager 130 (Figure 1) displays the new system status information in a System Status window panel (such as window panel 994 (Figure 18) or window panel 1002 (Figure 19)) on the display at the client computer 122/124. However, if the Refresh operation was not successful, process 770 proceeds to state 830 wherein the Recovery Manager 130 shows new status information for the items that the new status information has been successfully received (if any).

Returning to decision state 824, if the command was an Update, process 770 moves to decision state 834 to determine if the Update operation was successful. If so, process 770 continues to state 836 wherein the Recovery Manager 130 (Figure 1) displays an Update Successful indication in the appropriate Status window. However, if the Update operation was not successful, process 770 proceeds to state 838 wherein the Recovery Manager 130 displays an Update Failure indication in the appropriate Status window. Moving to state 840, the details of the command information are available, if the user so desires, by selecting a Details button (not shown). At the completion of any of states 828, 830, 836 or 840, process 770 completes at end state 842.

Referring to Figure 14, the Server System Status function 810 will now be described. Beginning at start state 870, function 810 proceeds to state 872 wherein each microcontroller on the microcontroller network bus 160 (Figure 2) checks to see if the address field of the system command received from the recovery manager 130 (Figure 1) at the client computer matches that of the microcontroller. Continuing at state 874, the addressed microcontroller executes a command, e.g., retrieve data or update data. Continuing at state 876 the addressed microcontroller sends a response message back on the microcontroller bus 160 to the controller that initiated the command, which is the remote interface controller 200 (Figure 2) in this situation.

Moving to decision state 878, function 810 determines whether additional items are selected for retrieval or update. If so, function 810 moves to state 880 to access the next command and then moves back to state 872 wherein each microcontroller again checks to see if it is addressed. The single addressed microcontroller performs states 5 872, 874 and 876. If there are no more items selected for retrieval or update, as determined at decision state 878, function 810 proceeds to a return state 882 where function 810 completes.

States 878, 880 and 882 are performed by the Recovery Manager 130 at the client computer 122/124. For example, if the user wanted system status on all the fans 10 by selecting the Fan icon 976 (Figure 18), the Recovery Manager 130 generates one command for each of a selected group of microcontrollers for retrieving fan information. Thus, a command to read fan information from CPU A controller 166 (Figure 2) is sent out and a response received, followed by a command to and response from Canister A controller 172, and so on through Canister B controller 174, 15 Canister C controller 176 and Canister D controller 178.

In one embodiment, the System Status windows provide the following status information:

System Status: Power Supplies

20 This window displays power supply status information. To obtain current information, click Refresh. This information includes:

- Present: Indicates the power supply is installed and present
- A.C.: Indicates whether the power supply is receiving A.C. power.
- 25 D.C.: Indicates whether the power supply is supplying D.C. voltage.
- Power: Indicates the server is On or Off.
- Output Voltages: Indicates the power (in volts) generated by each power supply line.

System Status: Temperature

This window displays information about the operational temperatures of the server. To obtain current temperature information, click Refresh. To apply any changes made in this window, click Update.

5

Temperature Sensor 1: Indicates the temperature measured by Sensor 1.

Temperature Sensor 2: Indicates the temperature measured by Sensor 2.

Temperature Sensor 3: Indicates the temperature measured by Sensor 3.

Temperature Sensor 4: Indicates the temperature measured by Sensor 4.

10 Temperature Sensor 5: Indicates the temperature measured by Sensor 5.

Warning Level: Shows the temperature warning level (in one embodiment, the default is 55 degrees Celsius). When any temperature sensor measures this level or higher, a warning is issued. To change the warning level, enter a new temperature and click Update.

15

Shutdown Level: Shows the temperature shutdown level (in one embodiment, the default is 70 degrees Celsius). When any temperature sensor measures this level or higher, the server is automatically shut down. To change the shutdown level, enter a new temperature and click Update.

20

Show Temp in Degrees: Select whether the temperatures are in Celsius or Fahrenheit.

System Overtemp?: Indicates whether the server temperature is above the Warning threshold.

25

System Status: Fans

This window displays server and group fan status information. To obtain current status information, click Refresh. The information that appears in this window includes:

30

	Location:	Indicates the location of the fan. Options include System Board and Groups A or B.
	Fans 1-6 (System Board), 1-2 (Group):	Indicates the location of the fan. For information on the physical location, click here Location icon.
5	Speed:	Displays the fan operating speed (in RPM).
	Speed Control:	Indicates the fan is operating at High or Low speed.
10	Fault Indicator LED:	Indicates the Fan Fault LED on the server enclosure is On or Off.
	Fault:	Indicates whether the fan failed.
	Low-speed Fault Threshold Speed:	Displays the low-speed fault threshold speed. When a fan drops below this speed, the fan is reported as failed. To change failure level, enter a new speed (in RPM) and click Update. In one embodiment, the speed is entered in increments of 60 (e.g., 60, 120, 180, etc.).
15		
20		
	Note: To view status information on a specific group of fans, change their speed, or modify the speed at which they are considered failed, double-click the fan group's icon.	
25	System Board Fans	
	This window displays information about the status of the system board fans. To obtain current information, click Refresh. To apply any changes made in this window, click Update.	

Group X Fans

This window displays information about the status of the fans in the selected group. To obtain current information, click Refresh. To apply any changes made in this window, click Update.

5

Canister X Fans

This window displays information about the status of the fans in the selected canister. To obtain current information, click Refresh. To apply any changes made in this window, click Update.

10

System Status: Processor

This window displays processor status information. To obtain current information, click Refresh. This information includes:

	CPU 1-4:	Indicates the location of the CPU.
15	Present:	Indicates whether the CPU is installed.
	Power:	Indicates whether the system is receiving power.
	Overtemp:	Indicates whether the system is running above operating temperature.
	Error:	Indicates whether a CPU internal error occurred.
20	NMI Control:	Indicates whether NMI control is active or inactive.
	Any Fault?:	Indicates whether faults or errors occurred on any installed processors.
	Bus/Core Speed Ratio:	Indicates the server's Bus/Core speed ratio, a relative indicator of processor performance.

25

CPU X Status:

This window displays status information for the selected CPU. To obtain current information, click Refresh. To apply any changes made in this window, click Update.

30	Present:	When selected, the CPU is installed.
	Power:	Indicates whether the system is receiving power.

Overtemp: Indicates whether the system is running above operating temperature.

Error: Indicates whether a CPU internal error occurred.

NMI Control: Indicates NMI control is active or inactive.

5

System Status: I/O Groups

This window displays I/O group status information. To obtain current information, click Refresh. This information includes:

10 PCI 1-4: Indicates whether a peripheral card is installed in the specified PCI slot.

PCI Power: Indicates whether the canister's PCI bus is receiving power.

System Status: I/O Canisters

15 This window displays I/O canister status information. To obtain current information, click Refresh. This information includes:

Status: Indicates the canister is inserted or removed.

20 PCI 1-4: Indicates whether a peripheral card is installed in the specified PCI slot.

PCI Power: Indicates whether the canister's PCI bus is receiving power.

System Status: Serial Numbers

25 This window lists the serial numbers of the system board, backplane, canisters, power supplies, and remote interface. To obtain current information, click Refresh.

System Status: Revisions

30 This window displays server component revision information for the backplane, system board, power supplies, I/O canisters or I/O groups, system interface and remote interface. To obtain current information, click Refresh.

WHAT IS CLAIMED IS:

1. A system for retrieving or updating system status for a computer, the system comprising:

a first computer;

a microcontroller capable of providing a retrieve or update system status signal to the first computer;

a remote interface connected to the microcontroller; and

a second computer connected to the first computer via the remote interface and communicating a retrieve or update system status command to the microcontroller.

2. The system defined in Claim 1, wherein the remote interface includes an external port for connection to the second computer.

3. The system defined in Claim 1, wherein the second computer is at the same location as the first computer.

4. The system defined in Claim 1, wherein the second computer is at a location remote to the first computer.

5. The system defined in Claim 4, additionally comprising a pair of modems, wherein a first modem connects to the first computer and a second modem connects to the second computer.

6. The system defined in Claim 5, wherein each modem further connects to the public switched telephone network.

7. The system defined in Claim 5, wherein each modem further connects to a cable network.

8. The system defined in Claim 5, wherein each modem facilitates connection to a satellite.

5 9. The system defined in Claim 1, wherein the remote interface includes a remote interface microcontroller that connects via a bus to the microcontroller.

10 10. The system defined in Claim 1, wherein the remote interface is responsive to a command sent from the second computer to retrieve or update system status from the microcontroller.

11. The system defined in Claim 1, wherein the first computer generates status information.

15 12. The system defined in Claim 11, wherein the second computer displays the status information.

20 13. The system defined in Claim 1, wherein the remote interface includes a power source independent of a power source for the first computer.

SYSTEM FOR DISPLAYING SYSTEM STATUS

Abstract of the Disclosure

5 A fault tolerant computer system for obtaining and displaying, or updating the
status of server components through a remote interface and either a local or remote
client machine without intervention of the server operating system software. The
remote machine accesses the server by use of a dial-in modem connection, while the
local machine accesses the server by a local serial connection. The components that
can be monitored include, but are not limited to, the following: Power Supplies,
10 Temperatures, Fans, Processors, I/O Groups, I/O Canisters, Serial Numbers, and
Revisions.

15 RJS-3383:sad
093097

Appendix A

Incorporation by Reference of Commonly Owned Applications

The following patent applications, commonly owned and filed on the same day as the present application are hereby incorporated herein in their entirety by reference thereto:

	Title	Application No.	Attorney Docket No.
5			
10	"System Architecture for Remote Access and Control of Environmental Management"		MNFRAME.002A1
	"Method of Remote Access and Control of Environmental Management"		MNFRAME.002A2
15	"System for Independent Powering of Diagnostic Processes on a Computer System"		MNFRAME.002A3
	"Method of Independent Powering of Diagnostic Processes on a Computer System"		MNFRAME.002A4
20	"Diagnostic and Managing Distributed Processor System"		MNFRAME.005A1
	"Method for Managing a Distributed Processor System"		MNFRAME.005A2
25	"System for Mapping Environmental Resources to Memory for Program Access"		MNFRAME.005A3
	"Method for Mapping Environmental Resources to Memory for Program Access"		MNFRAME.005A4
30	"Hot Add of Devices Software Architecture"		MNFRAME.006A1
	"Method for The Hot Add of Devices"		MNFRAME.006A2
	"Hot Swap of Devices Software Architecture"		MNFRAME.006A3
35	"Method for The Hot Swap of Devices"		MNFRAME.006A4

	Title	Application No.	Attorney Docket No.
	"Method for the Hot Add of a Network Adapter on a System Including a Dynamically Loaded Adapter Driver"		MNFRAME.006A5
5	"Method for the Hot Add of a Mass Storage Adapter on a System Including a Statically Loaded Adapter Driver"		MNFRAME.006A6
	"Method for the Hot Add of a Network Adapter on a System Including a Statically Loaded Adapter Driver"		MNFRAME.006A7
10	"Method for the Hot Add of a Mass Storage Adapter on a System Including a Dynamically Loaded Adapter Driver"		MNFRAME.006A8
	"Method for the Hot Swap of a Network Adapter on a System Including a Dynamically Loaded Adapter Driver"		MNFRAME.006A9
15	"Method for the Hot Swap of a Mass Storage Adapter on a System Including a Statically Loaded Adapter Driver"		MNFRAME.006A10
	"Method for the Hot Swap of a Network Adapter on a System Including a Statically Loaded Adapter Driver"		MNFRAME.006A11
20	"Method for the Hot Swap of a Mass Storage Adapter on a System Including a Dynamically Loaded Adapter Driver"		MNFRAME.006A12
25	"Method of Performing an Extensive Diagnostic Test in Conjunction with a BIOS Test Routine"		MNFRAME.008A
	"Apparatus for Performing an Extensive Diagnostic Test in Conjunction with a BIOS Test Routine"		MNFRAME.009A
30	"Configuration Management Method for Hot Adding and Hot Replacing Devices"		MNFRAME.010A
35			

	Title	Application No.	Attorney Docket No.
	"Configuration Management System for Hot Adding and Hot Replacing Devices"		MNFRAME.011A
	"Apparatus for Interfacing Buses"		MNFRAME.012A
5	"Method for Interfacing Buses"		MNFRAME.013A
	"Computer Fan Speed Control Device"		MNFRAME.016A
	"Computer Fan Speed Control Method"		MNFRAME.017A
	"System for Powering Up and Powering Down a Server"		MNFRAME.018A
10	"Method of Powering Up and Powering Down a Server"		MNFRAME.019A
	"System for Resetting a Server"		MNFRAME.020A
	"Method of Resetting a Server"		MNFRAME.021A
15	"System for Displaying Flight Recorder"		MNFRAME.022A
	"Method of Displaying Flight Recorder"		MNFRAME.023A
	"Synchronous Communication Interface"		MNFRAME.024A
20	"Synchronous Communication Emulation"		MNFRAME.025A
	"Software System Facilitating the Replacement or Insertion of Devices in a Computer System"		MNFRAME.026A
25	"Method for Facilitating the Replacement or Insertion of Devices in a Computer System"		MNFRAME.027A
	"System Management Graphical User Interface"		MNFRAME.028A
30	"Display of System Information"		MNFRAME.029A
	"Data Management System Supporting Hot Plug Operations on a Computer"		MNFRAME.030A

	Title	Application No.	Attorney Docket No.
	"Data Management Method Supporting Hot Plug Operations on a Computer"		MNFRAME.031A
	"Alert Configurator and Manager"		MNFRAME.032A
	"Managing Computer System Alerts"		MNFRAME.033A
5	"Computer Fan Speed Control System"		MNFRAME.034A
	"Computer Fan Speed Control System Method"		MNFRAME.035A
	"Black Box Recorder for Information System Events"		MNFRAME.036A
10	"Method of Recording Information System Events"		MNFRAME.037A
	"Method for Automatically Reporting a System Failure in a Server"		MNFRAME.040A
15	"System for Automatically Reporting a System Failure in a Server"		MNFRAME.041A
	"Expansion of PCI Bus Loading Capacity"		MNFRAME.042A
	"Method for Expanding PCI Bus Loading Capacity"		MNFRAME.043A
20	"System for Displaying System Status"		MNFRAME.044A
	"Method of Displaying System Status"		MNFRAME.045A
	"Fault Tolerant Computer System"		MNFRAME.046A
	"Method for Hot Swapping of Network Components"		MNFRAME.047A
25	"A Method for Communicating a Software Generated Pulse Waveform Between Two Servers in a Network"		MNFRAME.048A
	"A System for Communicating a Software Generated Pulse Waveform Between Two Servers in a Network"		MNFRAME.049A
30	"Method for Clustering Software Applications"		MNFRAME.050A

	Title	Application No.	Attorney Docket No.
	"System for Clustering Software Applications"		MNFRAME.051A
5	"Method for Automatically Configuring a Server after Hot Add of a Device"		MNFRAME.052A
	"System for Automatically Configuring a Server after Hot Add of a Device"		MNFRAME.053A
10	"Method of Automatically Configuring and Formatting a Computer System and Installing Software"		MNFRAME.054A
	"System for Automatically Configuring and Formatting a Computer System and Installing Software"		MNFRAME.055A
15	"Determining Slot Numbers in a Computer"		MNFRAME.056A
	"System for Detecting Errors in a Network"		MNFRAME.058A
	"Method of Detecting Errors in a Network"		MNFRAME.059A
20	"System for Detecting Network Errors"		MNFRAME.060A
	"Method of Detecting Network Errors"		MNFRAME.061A

RJS-3383:sad
093097

APPENDIX B

2024-2025

Provisional Patent Application

6391-709:

Title: REMOTE SOFTWARE FOR MONITORING AND MANAGING ENVIRONMENTAL
MANAGEMENT SYSTEM

Invs: Ahmad Nouri

The following documents are attached and form part of this disclosure:

1. *Maestro Recovery Manager Analysis - Problem Statement*, pp. 1-10.
2. *Remote Interface Board Specification*, Revision 2 13-000072-01, June 21, 1996, pp. 1-11.

Multiple Node Service Processor Network

A means is provided by which individual components of a system are monitored and controlled through a set of independent, programmable microcontrollers interconnected through a network. Further means are provided to allow access to the microcontrollers and the interconnecting network by software running on the host processor.

Fly-by-wire

A means is provided by which all indicators, push buttons and other physical control means are actuated via the multiple node service processor network. No indicators, push buttons or other physical control means are physically connected to the device which they control, but are connected to a microcontroller, which then actuates the control or provides the information being monitored.

Self-Managing Intelligence

A means is provided by which devices are managed by the microcontrollers in a multiple node service processor network by software running on one or more microcontrollers, communicating via the interconnecting network. Management of these devices is done entirely by the service processor network, without action or intervention by system software or an external agent.

Flight Recorder

A means is provided for recording system events in a non-volatile memory, which may be examined by external agents. Such memory may be examined by agents external to the network interconnecting the microcontrollers.

[illegible]

Extension by serial or modem gateway

Software means are provided to monitor and/or control a system using a remote agent. Means are provided for implementing an extension to the interconnecting network, converting protocols between media and communicating with and directing the microcontroller, and the state managed by those microcontrollers.

The following provisional patent applications, commonly owned and filed on the same day as the present application, are related to the present application and are incorporated by reference:

COMPUTER SYSTEM HARDWARE INFRASTRUCTURE FOR HOT PLUGGING MULTI-FUNCTION PCI CARDS WITH EMBEDDED BRIDGES (6391-704); invented by:

Don Agneta
Stephen E.J. Papa
Michael Henderson
Dennis H. Smith
Carlton G. Amdahl
Walter A. Wallach

COMPUTER SYSTEM HARDWARE INFRASTRUCTURE FOR HOT PLUGGING SINGLE AND MULTI-FUNCTION PC CARDS WITHOUT EMBEDDED BRIDGES (6391-705); invented by:

Don Agneta
Stephen E.J. Papa
Michael Henderson
Dennis H. Smith
Carlton G. Amdahl
Walter A. Wallach

ISOLATED INTERRUPT STRUCTURE FOR INPUT/OUTPUT ARCHITECTURE (6391-706); invented by:

Dennis H. Smith
Stephen E.J. Papa

THREE BUS SERVER ARCHITECTURE WITH A LEGACY PCI BUS AND MIRRORED I/O PCI BUSES (6391-707); invented by:

Dennis H. Smith
Carlton G. Amdahl
Don Agneta

HOT PLUG SOFTWARE ARCHITECTURE FOR OFF THE SHELF OPERATING SYSTEMS
(6391-708); invented by:

Walter A. Wallach
Mehrdad Khalili
Mallikarunan Mahalingam
John Reed

REMOTE SOFTWARE FOR MONITORING AND MANAGING ENVIRONMENTAL
MANAGEMENT SYSTEM (6391-709); invented by:

Ahmad Nouri

REMOTE ACCESS AND CONTROL OF ENVIRONMENTAL MANAGEMENT SYSTEM
(6391-710); invented by:

Karl Johnson
Tahir Sheik

HIGH PERFORMANCE NETWORK SERVER SYSTEM MANAGEMENT INTERFACE
(6391-711); invented by:

Srikumar Chari
Kenneth Bright
Bruno Sartirana

CLUSTERING OF COMPUTER SYSTEMS USING UNIFORM OBJECT NAMING AND
DISTRIBUTED SOFTWARE FOR LOCATING OBJECTS (6391-712); invented by:

Walter A. Wallach
Bruce Findley

MEANS FOR ALLOWING TWO OR MORE NETWORK INTERFACE CONTROLLER CARDS
TO APPEAR AS ONE CARD TO AN OPERATING SYSTEM (6391-713); invented by:

Walter A. Wallach
Mallikarunan Mahalingam

HARWARE AND SOFTWARE ARCHITECTURE FOR INTER-CONNECTING AN
ENVIRONMENTAL MANAGEMENT SYSTEM WITH A REMOTE INTERFACE
(6391-714); invented by:

Karl Johnson
Walter A. Wallach
Dennis H. Smith
Carl G. Amdahl

SELF MANAGEMENT PROTOCOL FOR A FLY-BY-WIRE SERVICE PROCESSOR
(6391-715); invented by:

Karl Johnson
Walter A. Wallach
Dennis H. Smith
Carl G. Amdahl

Problem Statement

◆ Introduction

Maestro Recovery Manager(MRM) is a software which locally or remotely manage a Raptor when a server is down or up, operating system died, LAN communication failed, or other server components failed .

User will be able to manage the server in very simple, usable, and friendly GUI environment. MRM use modem for remote and serial communication port for local to communicate with server for diagnostic and recovery.

Primary role of remote management is diagnosing and restoring service as quickly as possible in case of a service failure.

System administrator, LAN administrator in customer shop and NetFrame Technical support will be primary user for the system.

◆ Requirement Sources

MRM requirements comes from the following

- 1 - Focus Group (Customer Support and Training)
- 2 - User Walkthrough held by MRM team and Customer Support in Dec 96
- 3 - Down System Management Road map (96)
This road map is preliminary road map combined with Up System Management road map.
- 4 - MRM Road Map 97-98
This Road Map presented to Engineering Council Meeting on Mar 10, 1997.
- 5 - Raptor System, A Bird's Eye View.
- 6 - Raptor Wire Service Architecture

The following requirements have been identified for MRM

◆ Support Remote Management for Diagnostic and Recovery

Remote Management cover remote access to the Raptor Out Of Band management features. Remote Management will use Out of Band ,Control Diagnostic and Monitor Subsystem (CDM) remote management to cover the other high value added remote management functions. primary role of remote management is diagnosing and restoring service as quickly as possible in case of service failure.

◆ **Support Remote Management ... (continue)**

The control of Raptor is completely "Fly By Wire" - i.e. no physical switch directly controls any function and no indicator is directly controlled by system hardware. All such functions referred to as "Out of Band " functions are controlled through a CDM. CDM basic functions are available so long as A/C power is available at the input to any of the power supplies.

CDM Subsystem supervises or monitors the following system features.

- **Power supplies** - Presence, status, A/C good, Power on/off and output voltage.
- **Environment** - Ambient and exhaust temperatures, Fan speed, speed control, Fan fault and overtemp indicators.
- **Processor** - CPU Presence, Power OK, Overtemp and Fault, NMI control, System reset, Memory type/ location and Bus/Core speed ratio.
- **I/O** - I/O canister insertion/removal and status indicator , PCI card presence, PCI card power and smart I/O processor Out Of Band control.
- **Historical** - Log of all events, Character mode screen image, and Serial number

◆ **Support for Object Oriented Graphic User Interface**

OO-GUI is graphic user interface with the following characteristic.

- **User task oriented**
It uses tasks which user familiar and daily working with. User does not need to learn the tasks.
- **User objects**
It uses objects which user working with during her or his daily work.
- **Simplicity and useability**
It is very simple to use and does not need long learning period.
- **Point and click with context sensitive help**
Context sensitive help and point and click will help user to be very productive and get any information he needs on specific object or field or subject.
- **Drag and drop**
Drag and Drop capability works with user object very well to accomplish the tasks.

◆ **Release Requirements (MRM V2.0, 4Q96)**

Maestro Recovery Manager (MRM) will support the following features locally through serial port and Wire Service Remote Interface card on the Raptor16.

MRM provide user friendly GUI with point and click capability to perform the following tasks which reviewed and accepted by the Focus Group for 4Q96 release.

- **Power On /Off**
MRM support Power On/Off the server.
User can do this task by right mouse click on the server object in the screen and see the result.
- **Display Flight Recorder.**
While the server is working , Wire Service record all the server information in the 64K NVRAM. After the server failed, MRM will display the system log recorded in the NVRAM. User can evaluate the information and find the cause for the server failure. This can be done by right mouse click on the Flight Recorder object in the screen.
- **System Reset**

MRM support rebooting the server by right mouse click on the server object in the screen. This is warm reboot of the server and works as pushing the "reset" button on the server.
- **Save**

MRM will support saving Flight Recorder data, so user can send the file to the technical support for further diagnostic and recovery. It also can save the response for any Wire Service command failure.
- **On Line help**
MRM will support online help contains overview, Getting Started, MRM tasks, Diagnostic and Recovery, and BIOS help.
- **B0 back plane support**

MRM will support the server with B0 back plane . Server with B0 back plane display wrong time stamp. MRM uses NetWare 4.11 Operating system time stamp to display correct time stamp.

◆ **Release Requirements (MRM V2.1, 1Q97)**

Maestro Recovery Manager (MRM) will support Raptor16 Phase 2 for next release as follow. This release will delivered to customer by NetFrame Customer Support on CD.

MRM V2.1

MRM V 2.1 will support the MRM V2.0 plus the following new features for next release.

- **User Walkthrough Requirements held on Dec 17, 1996**
- **Recovery and Diagnostic help.**
This help enable the user to display help based on message source or severity (fatal error, error, warning,). In each case the help inform the user the cause for the error and what steps to take to solve the problem.
- **C0 /E18 back plane support**
- **New C0 back plane Wire Service, Diagnostic, and BIOS message structure**

◆ **Release Requirements (MRM V2.2 , 2Q97)**

MRM V2.2 for Raptor 16

MRM V2.2 will support MRM V2.1 plus the following new features.

● **Remote connection via modem**

MRM supports remote connection to an NF9000-16 via an external modem. MRM needs one external modem for client side and one external modem for the server side. The client modem can be installed and set up via the Windows NT/95 standard control panel/Modems installation. The server side modem has to be set up and connected to the server. Details of installation and setup for the modem are provided in the NF9000 Maestro Recovery Manager Installation Guide. **MRM does not support internal modems.**

The following external Hayes compatible modems have been tested and worked with MRM.

* **Client Modem**

US Robotics Sportster 33.6 Fax modem
ZOOM fax MODEM V.34X 33.6

* **Server Modem**

ZOOM fax MODEM V.34X 33.6

● **System Status**

MRM supports retrieve and update of the system status components.

System status comprised of the following components.

* **Power Supplies**

The following information will be displayed for this feature.

1. Presence
2. Status(ACOK, DCOK)
3. Power On/off
4. Output voltage (Analog measure of main supply + VREF)

*** Temperatures**

We will support four types of temperature for 5 sensors and display Operating (10 -35 degree C) and None-operating (-40 to 70 degree C).

1. Temperature of all sensors
2. Warning temperature
3. Shutdown temperature
4. System over temp

*** Fans**

There are different type of fans in the system such as system fan and canister fan. All of them have the common following characteristics.

5. Speed (speed data)
6. Control (LOLIM, can be set to LOW or HIGH)
7. Fault (LED, Bits)

*** Processors**

There are 4 CPU in the Raptor16 with the following parameters.

1. CPU presence
2. CPU Power OK
3. System over temp
4. System Fault
If system over temp or CPU internal error or system power failure.
then wire service report System Fault
5. CPU Error
If internal CPU error occurred , then report CPU error
6. CPU NMI control
7. System Board Bus/Core speed ratio

*** I/O Canisters**

There are four canisters available

1. I/O canister (insertion, removal)
This shows presence bits for canister.
2. PCI cards
This reflect PCI card slots [1-4] presence
3. PCI card power
This controls canister PCI slot power

*** Serial Numbers**

This is the last known serial data for the following server parts

1. Back plane
2. Canister 1-4
3. Remote Interface (not implemented)
4. System Board
5. Power supply 1-2

*** Revisions**

MRM will support the following chips revision

1. Back Plane
2. System board
3. Power Supply 1- 2
4. Canisters 1- 4
5. Local Interface
6. Remote Interface

● Context-sensitive Help

All elements in the window such as icon, entry field, push button, and radio button have context-sensitive help. This help contains the following type.

*** What's this**

It shows description of each elements in the window which it is not disabled. This can be accomplished by right mouse click on each element in the window.

*** Help push button.**

This display general help for all windows.

*** F1 Key**

The key displays the help for any entry field in the window.

● Print

MRM supports printing of flight recorder based on all messages, warning & errors, and errors with one type of font.

- **Password**

Wire Service password is originally set by Manufacturing to "NETFRAME" (case sensitive) for every NF9000-16 server.

MRM provides a password changing mechanism for the Wire Service system. For security purposes, MRM only allows the password to be changed via the local serial port connection and not via the remote connection

- **Support B0/E18 on NT4.0 server**

MRM supports B0/E18 configurations by utilizing a time stamp software component which resides on the NT4.0 server.

Installation instructions for the time stamp are provided in the NTReadMe file on a floppy disk packaged with MRM.

MRM requires the NetFRAME NT Value Add software to operate.

The NetFRAME NT Value Add software will automatically install the time stamp for you. If you have not installed NetFRAME NT Value Add, then you need to install the time stamp provided for you on the NTSup floppy disk.

- **Support for InstallShield**

InstallShield setup software is used to install MRM on the client workstation.

- **Delivery**

MRM package contains the following.

- * **NF9000 Maestro Recovery Manager CD release.**
This CD contains MRM software and documentation.
- * **Two support floppy disks for NF9000-16 B0 back plane for NT and NetWare.**
- * **Boxes contain above items, Remote Interface Card, adapter, cables, and documentation.**

- **Dependency**

MRM version 2.2 depends on the following items:

- Remote Interface chip provided by Wire Service(Firm Ware) department.
- Remote Interface card provided by Hardware Engineering department.
- Remote Interface boxes, cables, and power adapters provided by Manufacturing.

◆ **Release Requirements (MRM V2.2, 2Q97)**

MRM V2.2 for Raptor 8

MRM V2.2 for Raptor 8 has the same features as MRM v2.2 for Raptor16 with the following different .

- **Support for C0 back plane and F18 BIOS**
- **System Status**

The following components of System Status are different from MRM V2.2 for Raptor16.

*** Power Supplies**

1. User can not turn off and on specific power supply.
2. Raptor 8 has three power supply.
3. There are no DC (OK, BAD) for Raptor8.
4. AC for all power supplies are good all the times.

*** Fans**

1. Four system board fans in front
2. Two system board fans (Storage fans) in back
3. Group A and group B sharing two fans.

*** I/O Groups**

1. Group A contains 4 PCI card slots
2. Group B contains 4 PCI card slots.

*** Serial Numbers**

1. Serial number for Group A and B fans are the same.
2. There is serial number for power supply # 3.

*** Revisions**

1. Group A and B fans have the same revision.
2. There is revision for power supply #3

Maestro Recovery Manager Analysis - Problem Statement

- **Delivery**

MRM package contains the following.

- * **NF9000 Maestro Recovery Manager CD release.**
This CD contains MRM software and documentation.
- * **Boxes contain above items , Remote Interface Card, adapter, cables, and documentation.**

**Remote
Interface Board
Specification**

Revision 2
13-000072-01
June 21, 1996

Tahir Sheikh
NetFRAME Systems, Inc.

2025-04-10 14:00:00

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Mechanical	6
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Environment	9

Overview:

This board is an interface between Raptor Wire Services and an external modem. The system status and commands are passed through the RS232 connection at the modem side to the Wire Services bus, the I2C bus, controlled through an on board PIC16C65. The I2C signals are translated by the PIC16C65 into an eight signal RS232 protocol and passed through a voltage level translator LT1133A, with baud capable of reaching the speed of 120k. A 25 pin D-Sub connector resides on the other side of the voltage level translator.

The system status storage is through a 32Kx8 SRAM, with an external latch for latching the higher addressing bits of the data RAM. A signal powered EPROM is used for storing board ID information.

The board is powered through 7.5V and 700mA supply unit, and is an alternative source for the bias powered partition of the Wire Services. The bias powered block includes an NV-RAM and a PIC16C65 which are resident on the Raptor back plane. The power source is regulated through a high frequency switching regulator.

1.0 Features

The designed features are as follows:

1.1 I2C Interface

The two wires interface is brought from the Raptor and passed to the PIC16C65 using an RJ45. A bus extender 82B715 is connected between the external interface to the local I2C bus. Port C bit 3 is the clocking bit, and Port C bit 4 is the data line.

1.2 RS232 Protocol

The communication with the modem is based on the RS232. Microcontroller PIC16C65 is used to generate the receive and the transmit signals, where the signal levels are transposed to the RS232 levels by the LT1133A. The 3 transmit signals, RTS, SOUT and DTR are from Port A bits 2, 3 and 4, where as the 5 receive signals are from two ports, DCD, DSR from Port C 1,0 and SIN, CTS and RI from Port A 5, 0, 1.

The 25 pin RS232 pin connection is used instead a 9 pin connector, since this type of connector is more common than the other. All the extra pins are no connect except the pins 1 and 7, where pin 1 is chassis ground and pin 7 is a signal ground.

The connection through LT1133A can be run up to 120k Baud and is ESD protected to +/- 10kV.

The short voltage at the output can be +/- 30V and is isolated to the forward direction only.

1.3 PIC16C65 and 32Kx8

A 32Kx8 SRAM is available for storage and transfer between the internal Wire Services and the external remote interface. Port D is the address port, while an external 74ABT374 is for expanding the address range to 15 bits. Port B is the data bus for the bi-directional data interconnect. Port E is for the SRAM enable, output tristate and the write control signals.

The PIC16C65 is designed for a frequency of 12MHz. An LED is also connected to the Port C bit 5.

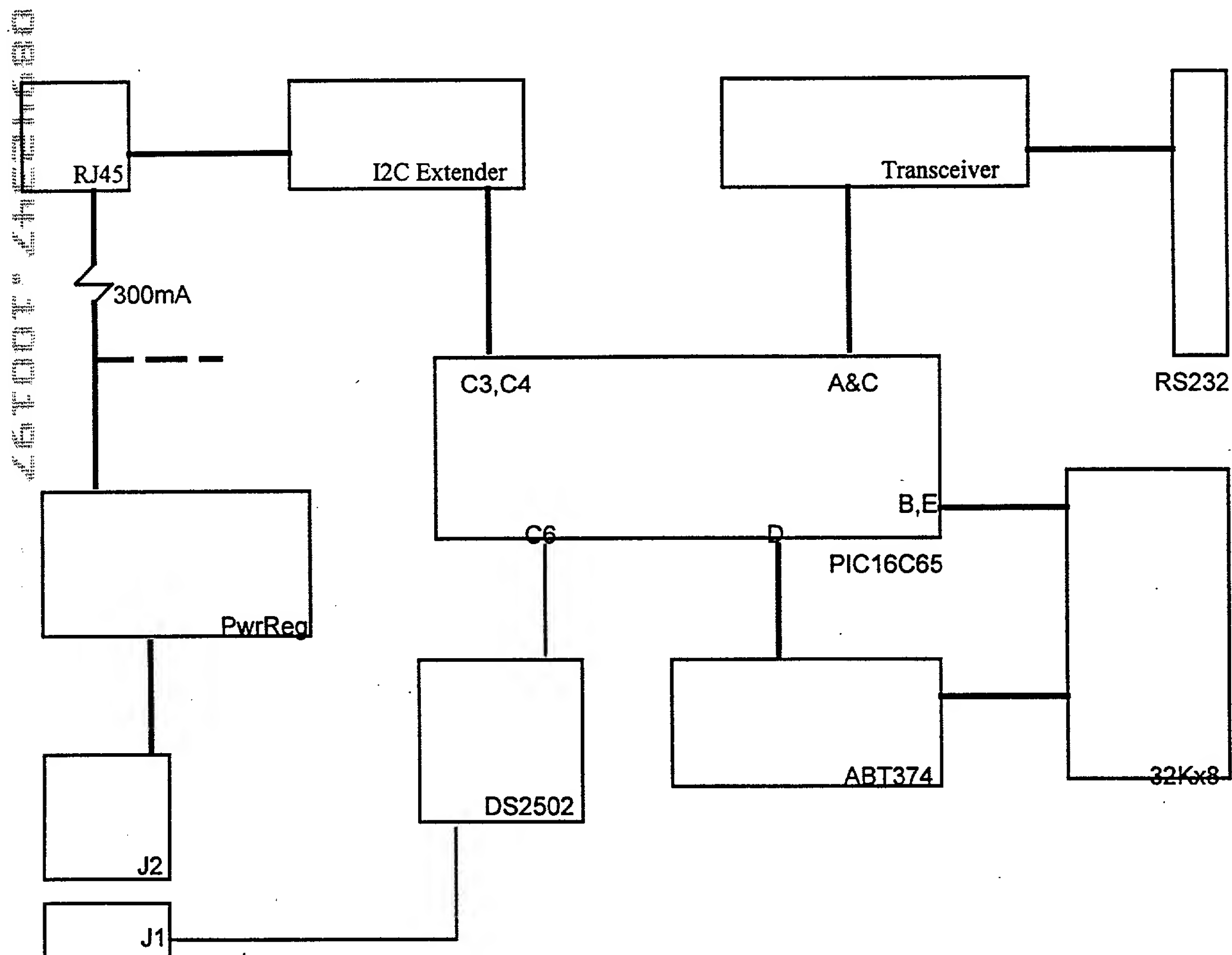


Figure 1: Remote Interface Interconnect

1.4 Serial ID EPROM

DS2502 is for storing board ID, connected to PIC16C65 Port C bit 6. The programming is handled through a jumper applied through connector J1. DS2502 is a signal powered, retaining the charge into a capacitor, sourced through the data line.

2.1 Alternative Power Source

The board is powered through 7.5V and 700mA (or 800mA which ever available) supply unit. After regulating the supply, it is an alternative source for the bias powered partition of the Raptor Wire Services. The bias powered block includes an NV-RAM and a PIC16C65 which are resident on the Raptor back plane.

The power source is regulated through a high frequency switching regulator based on Linear Technology LT1376. The input to the regulator circuitry is off a wall mounted adapter. The regulated output is consumed locally and 300mA are sourced to the Raptor Wire Services through a fuse and an RJ45 P1.

2.2 Power Consumption

The following is an average estimated power consumption with the board running at a base frequency of 12MHz.

PIC16C65	Microcontroller	30mA
82B715	I2C Extender	10mA
32Kx8	SRAM	80mA
LT1133A	Transceiver	70mA
374	Latch	30mA
	Misc.	60mA

		280mA
	Alt. Source	300mA

580mA

LT1376, L1, D2, D3, etc.

1.45 Watts max.

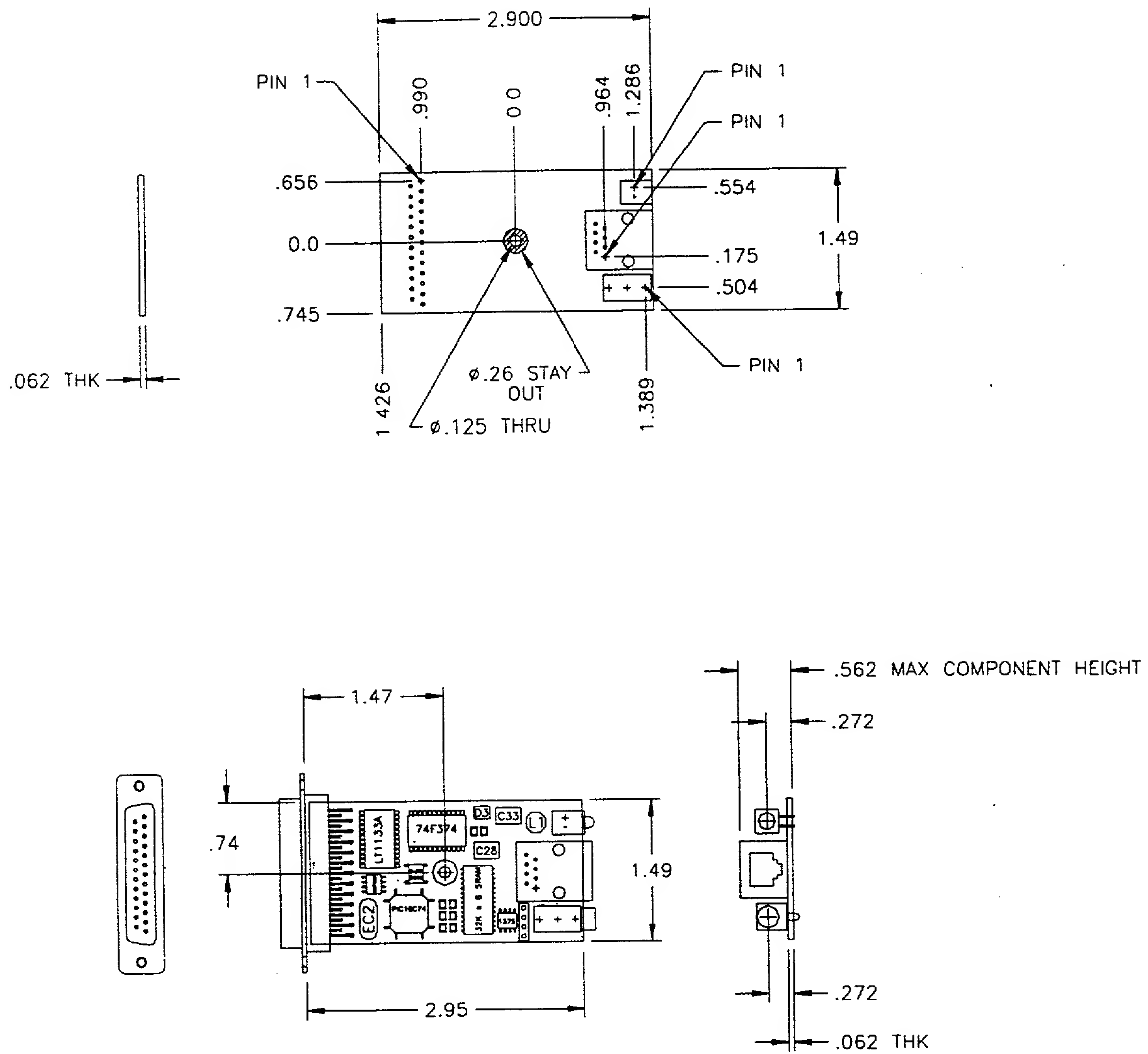


Figure 2: Mechanical Orientation

2.3 Board Layout

The board is based on controlled impedance of 60 Ohms \pm 10%, with 6 layers and test points for all signals. The width is restricted by the dimension of the RS232 due to the mounting constrains. The board is dual sided with active components kept on the top side only.

The high frequency bypass is kept with .1uf and .001uf, where the charge storage is kept by two 33uf and two 1uf capacitors.

The location and mounting of the power connector and the LED are kept such that the both sides of the cabinet are identical, therefore interchangeable.

3: Enclosure

The enclosure is planned to be Injection Molded Aluminum, a side view is in figure 3. Aluminum instead of plastic is selected due to the regulator heat, and EMI shielding.

The board connects at three locations between the top and the bottom enclosures. Two locations are based on the clamp shell design at the D-Sub and the RJ45, two opposite ends of the enclosure. The third location is a mounting hole in the center of the enclosure.

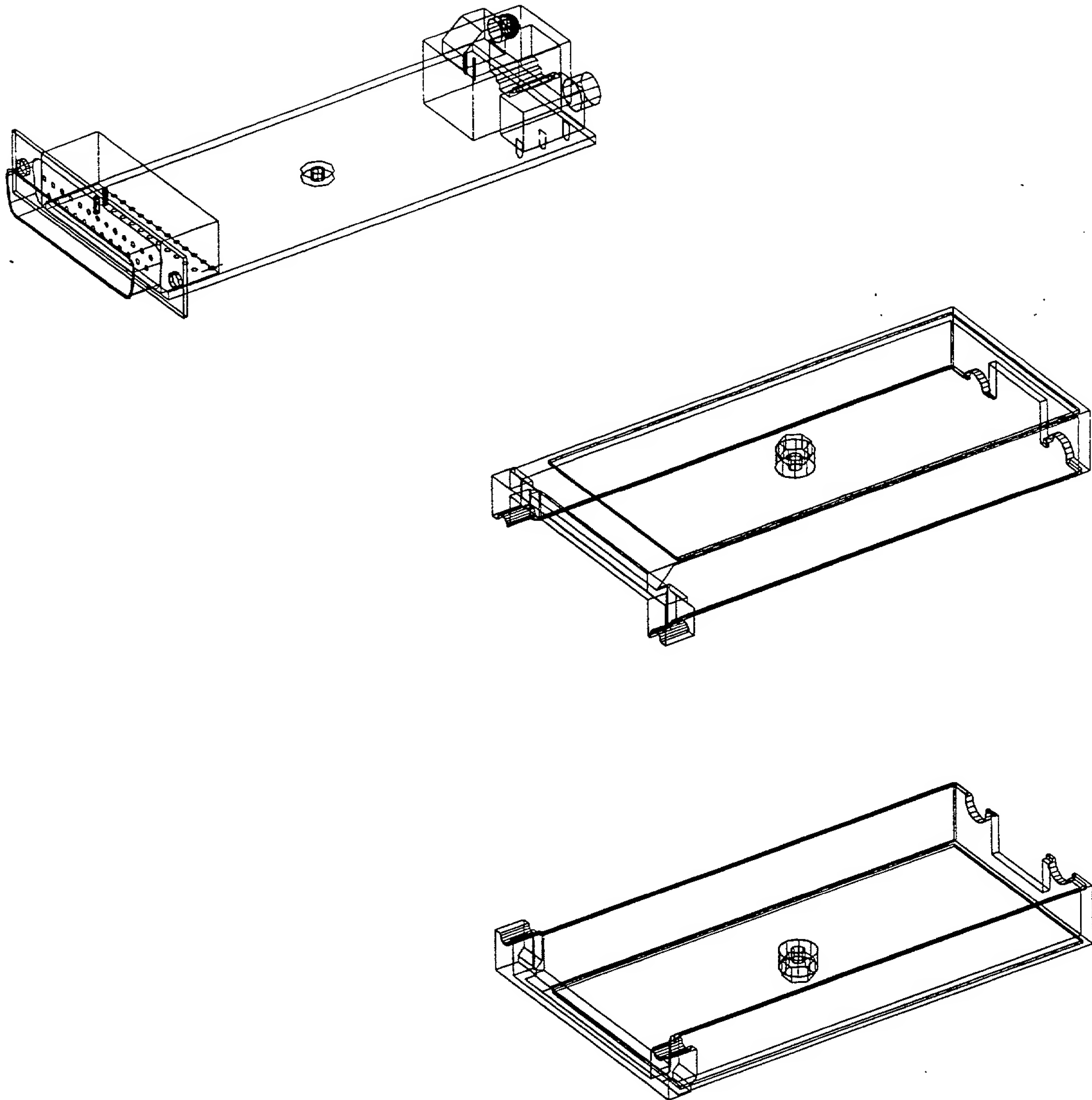


Figure 3: Board and Enclosure Isometric View

4.0 Environment

The environmental specification is based on assumptions:

The environment is Ground Fixed.

The "Quality Level of II" is used.

Bellcore Method I, Parts Count Method, Case 2 for prediction.

Burn-in time 120 hours.

Operated at 40C and 50% rated electrical stress.

4.1 Environmental Specification:

MEAN TIME BETWEEN FAILURE

2.445250e+06 Hours

This number is calculated based on the Bellcore Technical Reference TR-NWT-000332, Reliability Prediction Procedure for Electronic Equipment, Issue 4, September 1992.

ALTITUDE

Operating -100 to 10,000 feet
Non-Operating -100 to 40,000 feet

HUMIDITY

Operating 10% to 80% R.H., Maximum Gradient 10% per hour
Non-Operating 5% to 90% R.H., Maximum Gradient 10% per hour

TEMPERATURE (ambient)

Operating 10 to 40 degrees C Maximum
Gradient 10 degrees C per hour
Non-Operating -40 to 70 degrees C
Maximum Gradient 10 degrees C per hour

SHOCK

Operating

Magnitude 2 G's (peak)
Duration 11 ms
Waveform Half Sine

Non-Operating

Magnitude 10 G's (peak)
Duration 11 ms
Waveform Half Sine

VIBRATION

Operating

Frequency Range 5 to 500 Hz
Magnitude 0.010 inch peak to peak displacement
Acceleration 0.20 G's peak

Non-Operating

Frequency Range 5 to 500 Hz
Magnitude 0.010 inch peak to peak displacement
Acceleration 0.50 G's peak

DROP (PACKAGED)
ASTM D4169

ELECTRICAL

Nominal Line	115 VAC or 230 VAC @ 50/60 Hz autoranging
Line Deviation	90-130 VAC & 180-256 VAC @ 47-63 Hz
Line Transient/Surge Susceptibility	1.25 x highest rated nominal voltage or 300 Vrms, whichever is less, for 1 second.

ELECTRO-MAGNETIC COMPATIBILITY

FCC, Class A under FCC Rule 15, Subpart B, conducted and radiated.

Canadian Radio Interference Regulations, C.R.C., c.1374, Sec. 2, as amended in The Canadian Gazette, Part II, Vol. 122, No. 20, dated Sept. 28, 1988.

European EMC Directive (89/336/EEC) CISPR 22 (Class B).

IEC 801-2:1984 8 kV air discharge

IEC 801-3:1984 3 V/m, 27-500 MHz

IEC 801-4:1988 1 kV mains, 500 V other.

SAFETY AGENCIES

UL, CSA, VDE, JIS

Electrostatic Discharge

Air Discharge	2.5 to 5.0KV	no errors allowed
	5.1 to 10.0 KV	recoverable errors through system allowed
	10.0 to 20.0KV	recoverable errors through power cycling allowed
Contact Discharge	0 to 8.0KV	recoverable errors through power cycling allowed

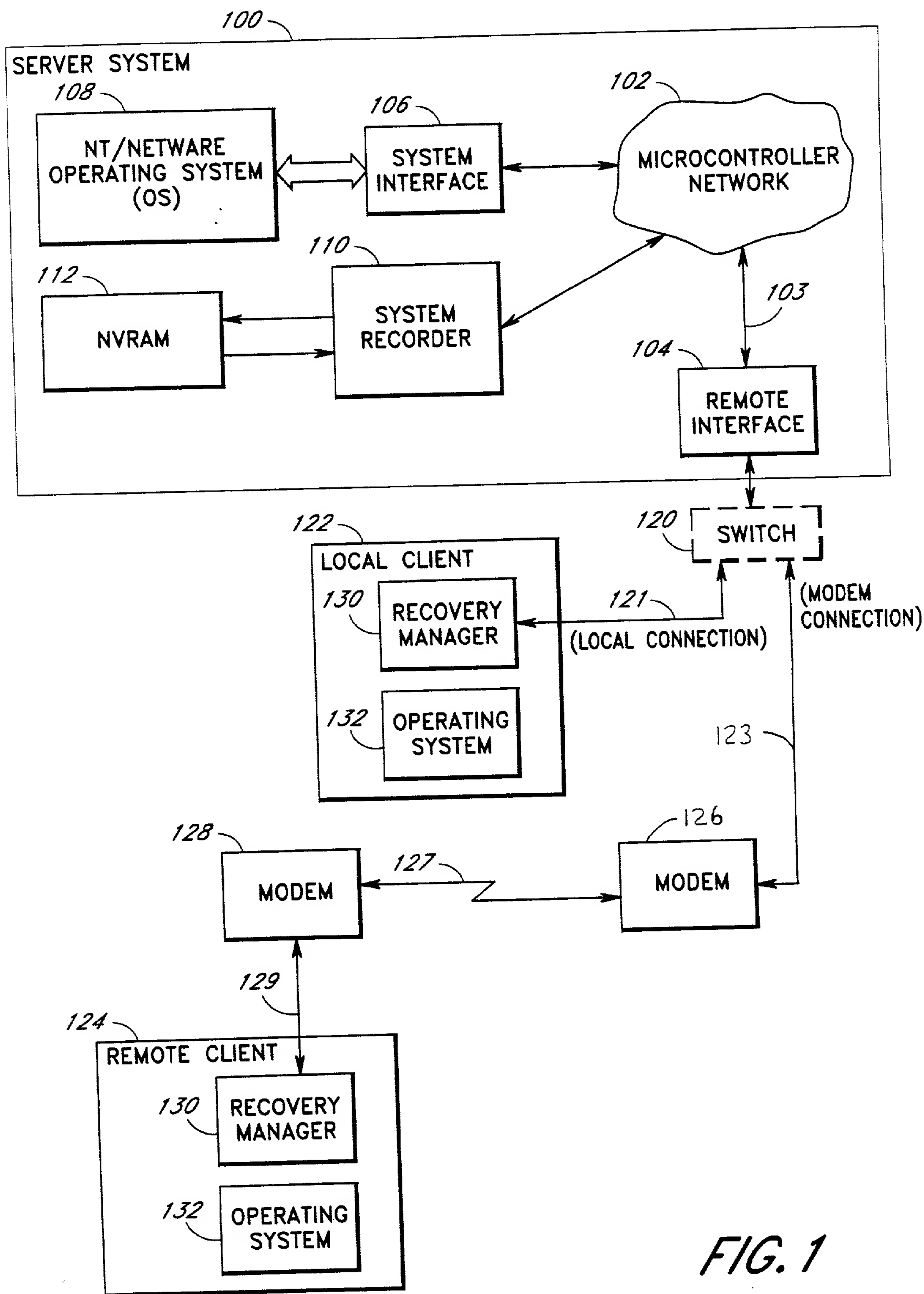
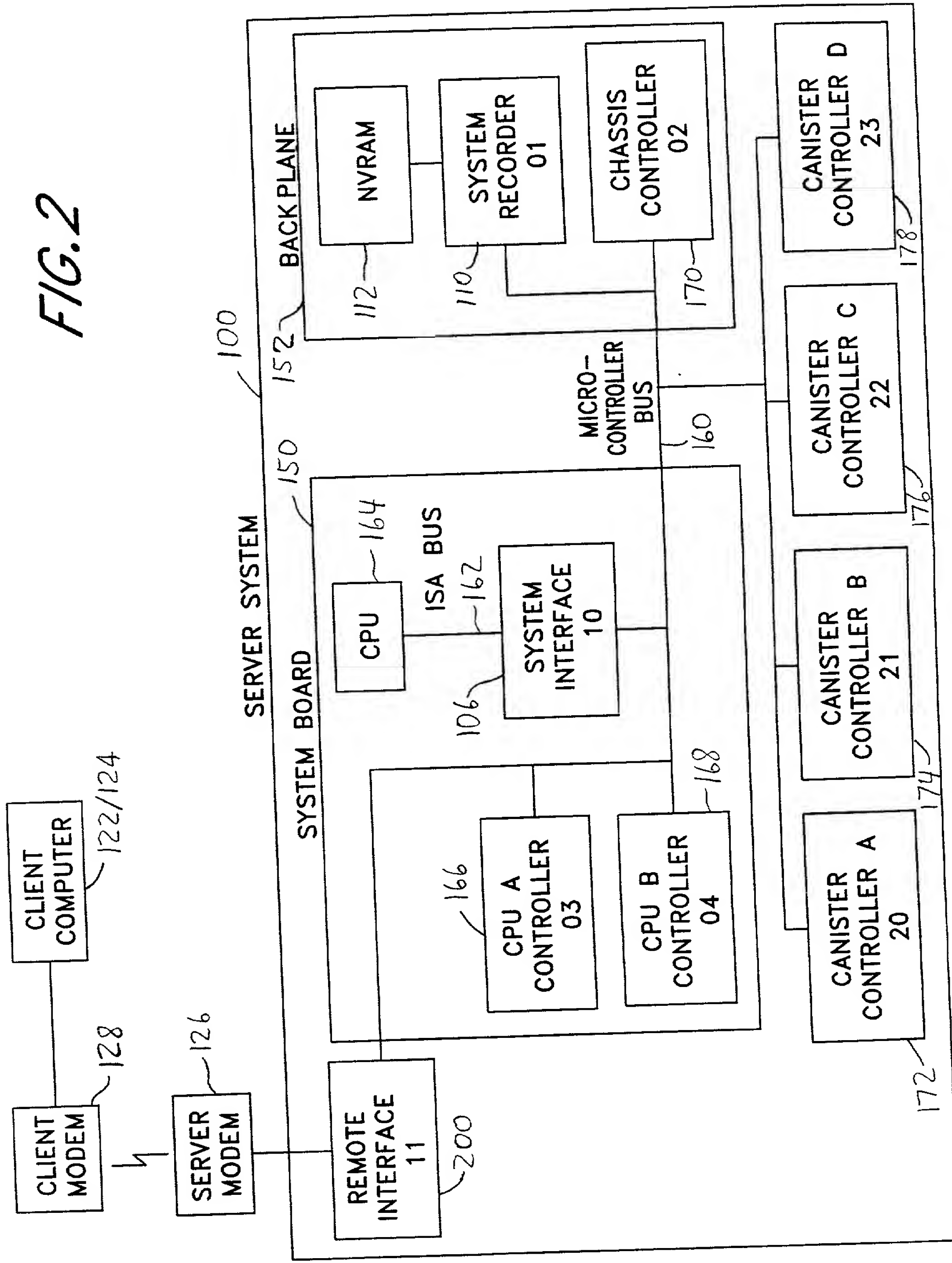


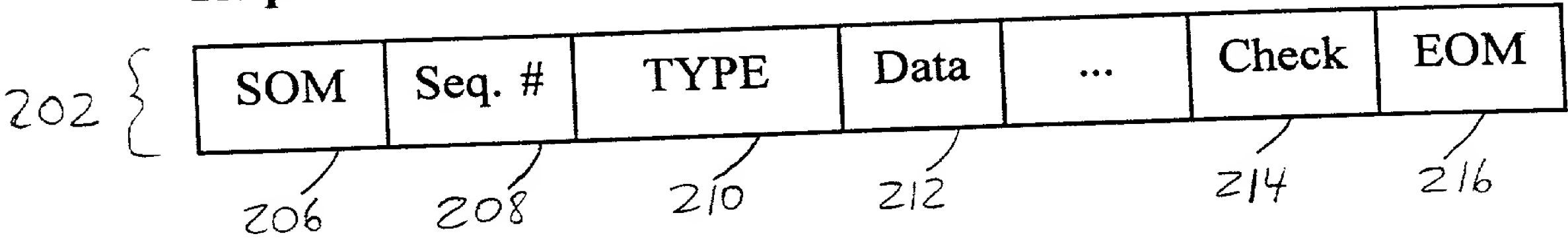
FIG. 1



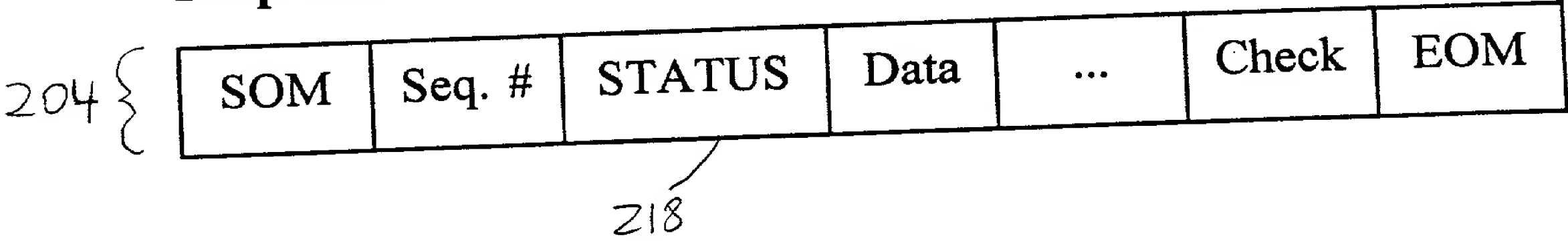
Remote Interface Serial Protocol Message Formats

201
↓

Request:



Response:



Event Interrupt

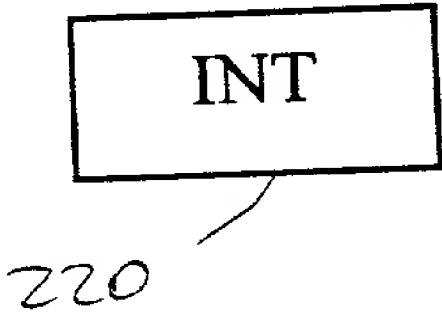


FIG. 3

POWER-ON PROCESS

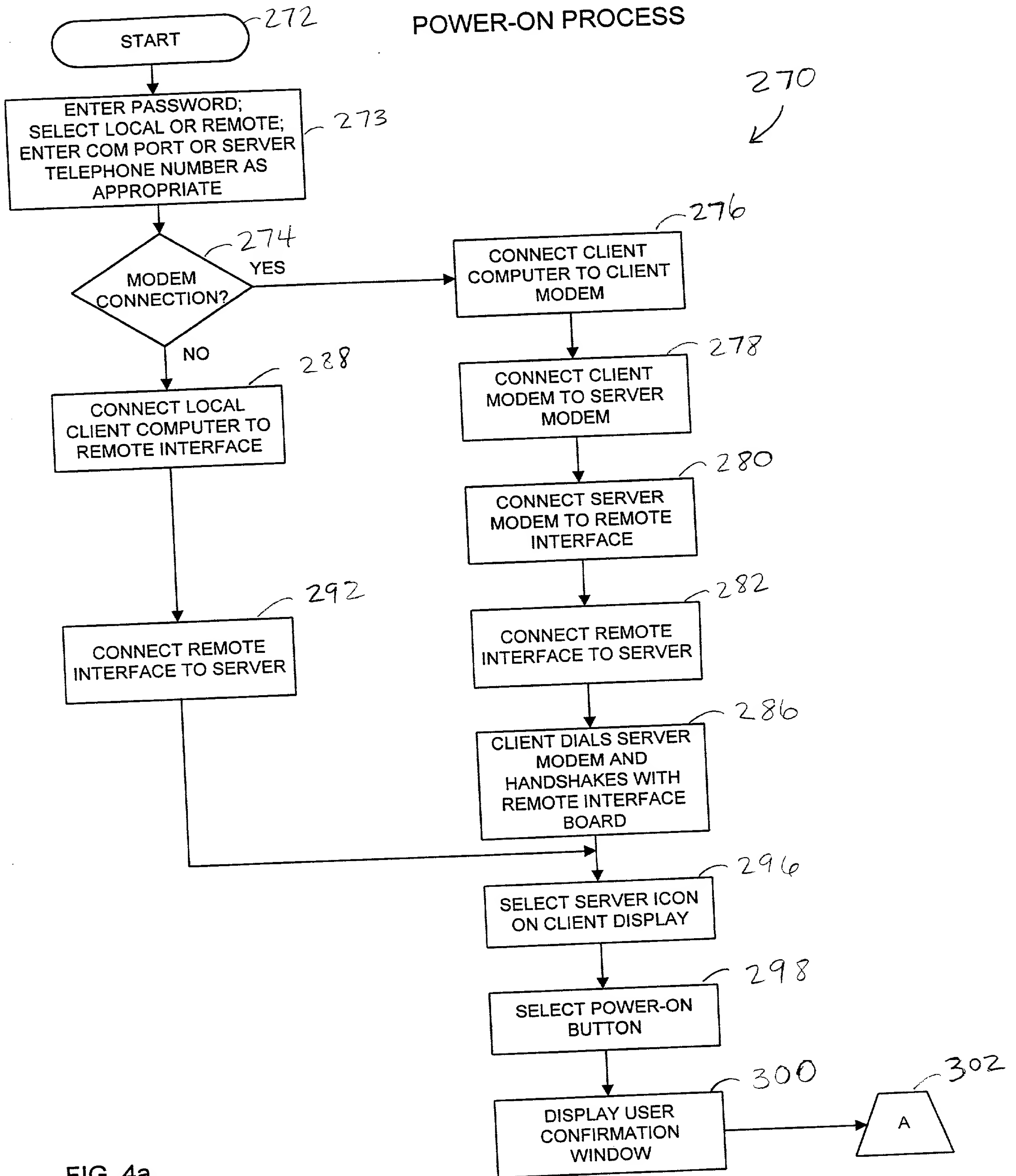


FIG. 4a

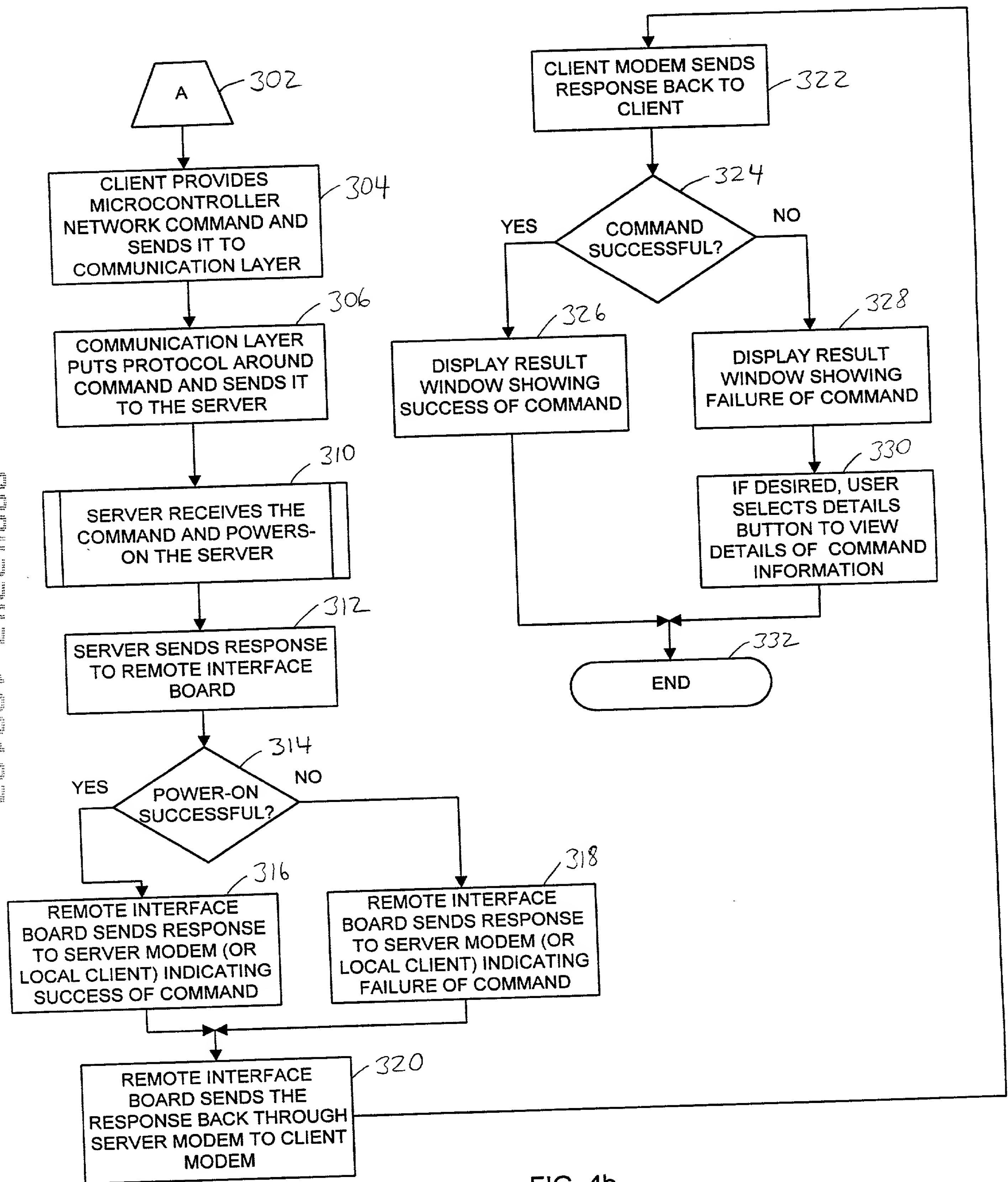
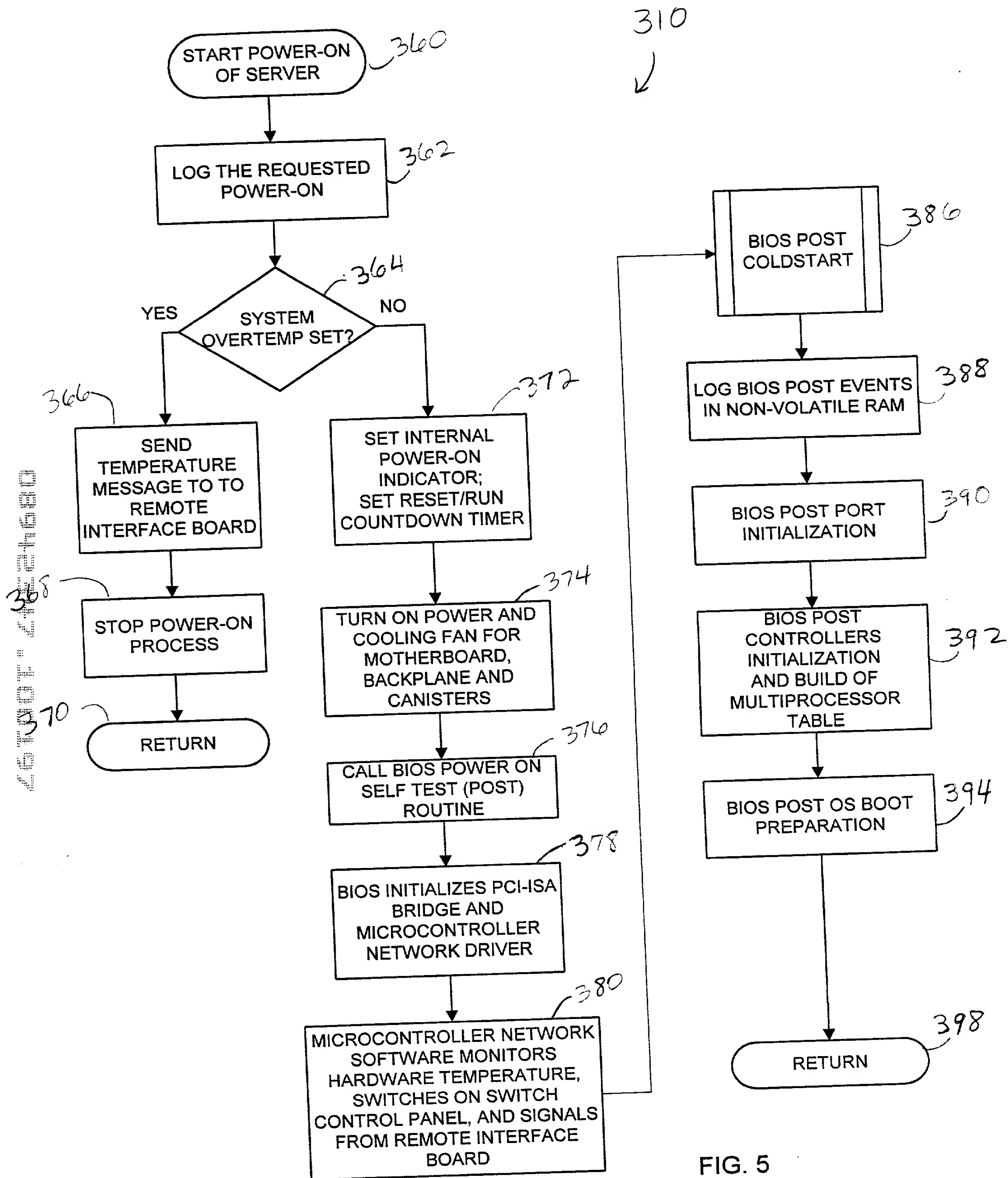
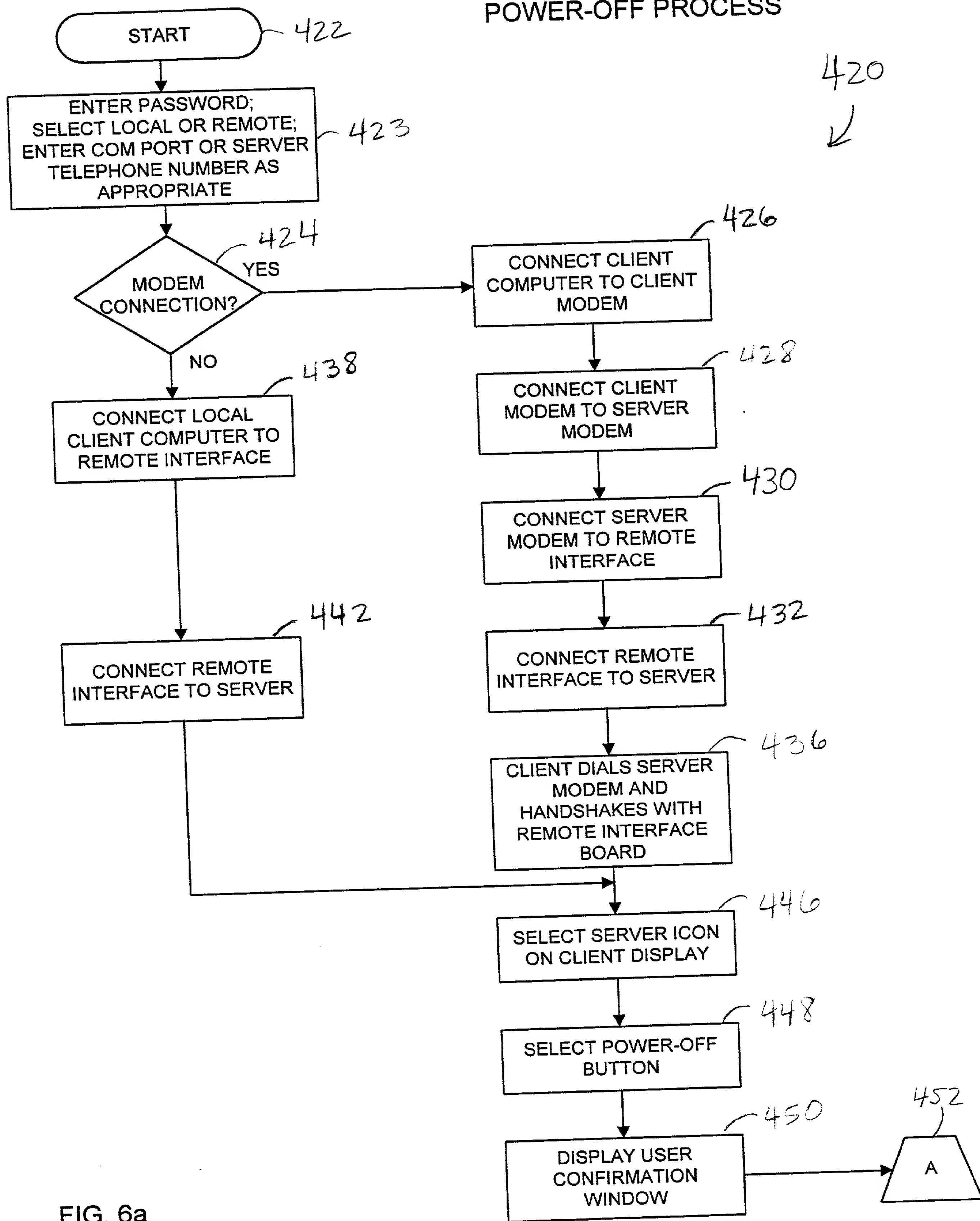


FIG. 4b



POWER-OFF PROCESS



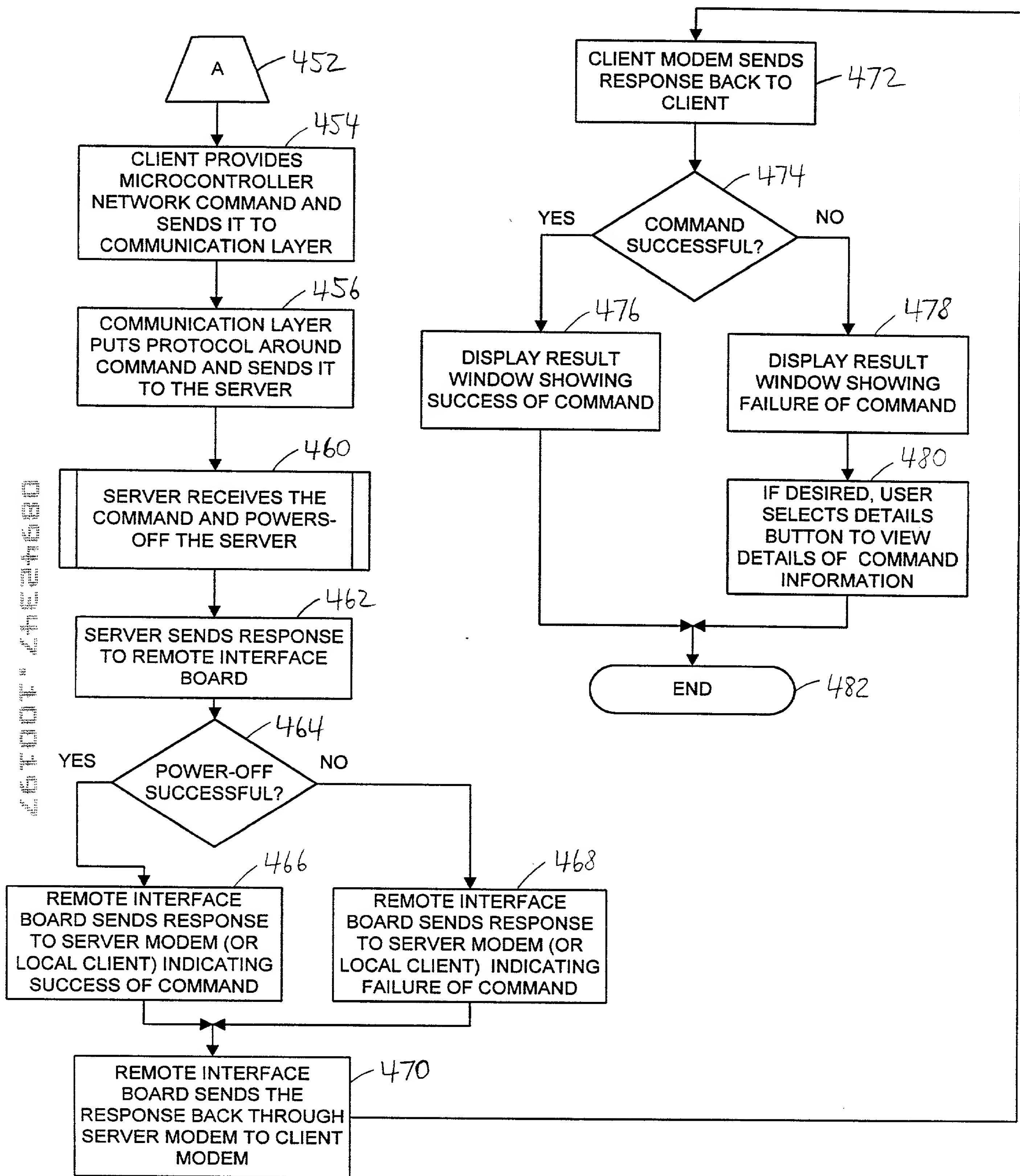
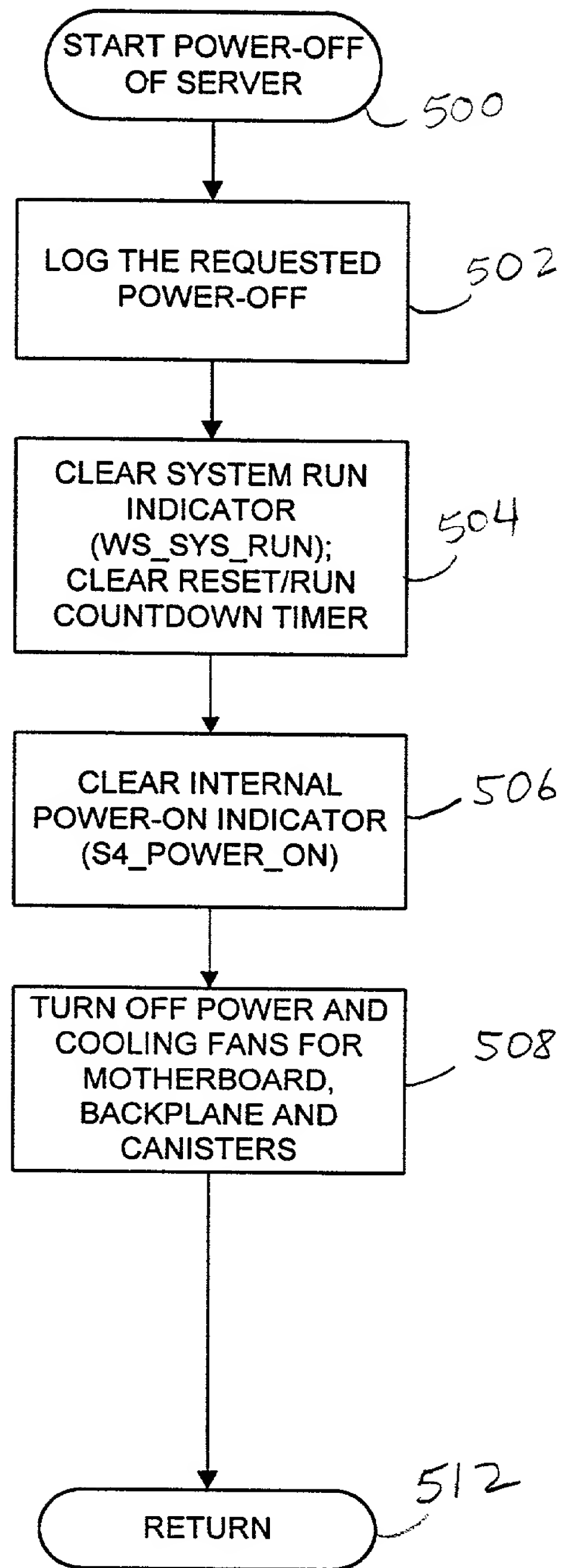


FIG. 6b



460
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FIG. 7

RESET PROCESS

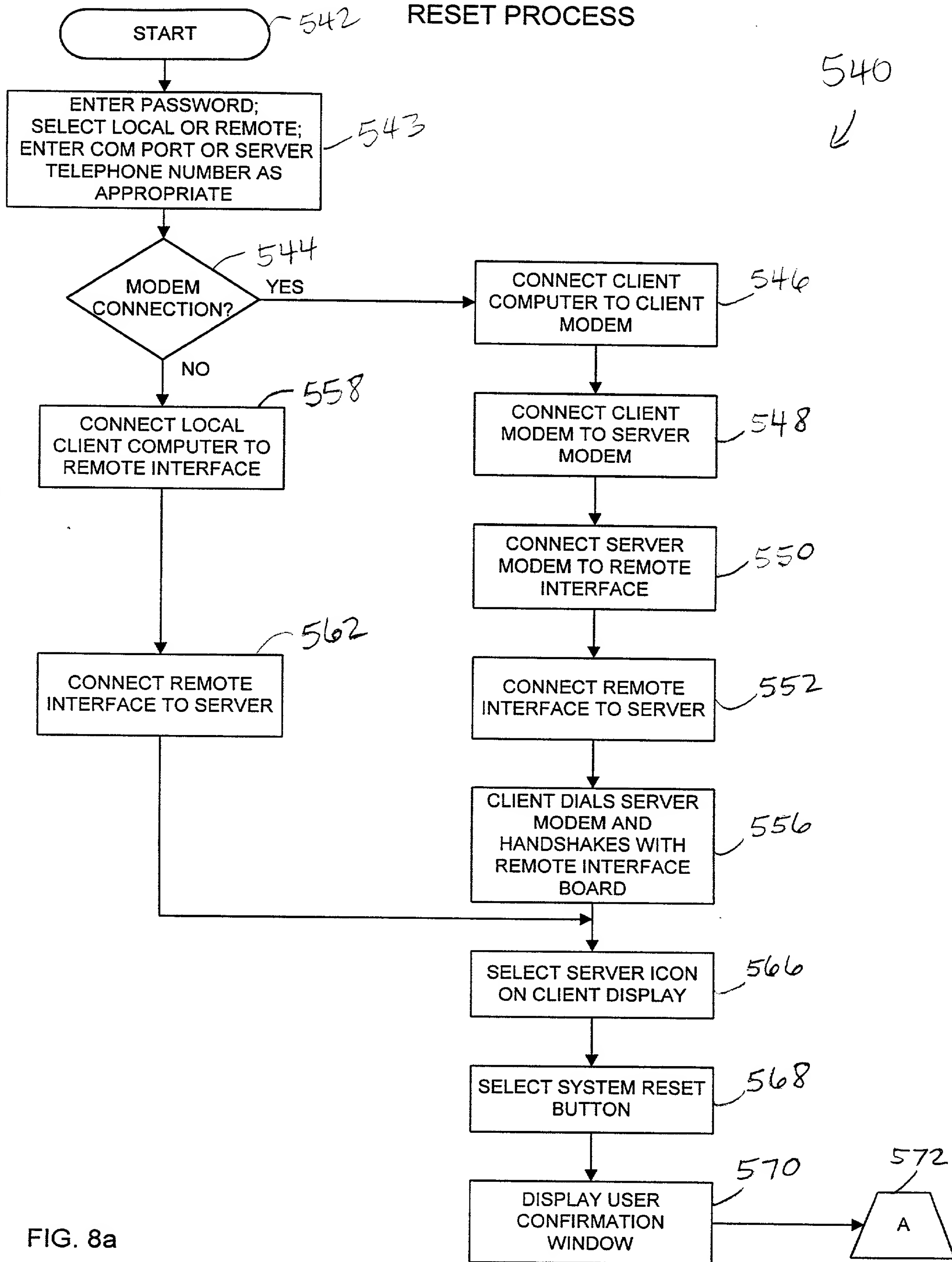


FIG. 8a

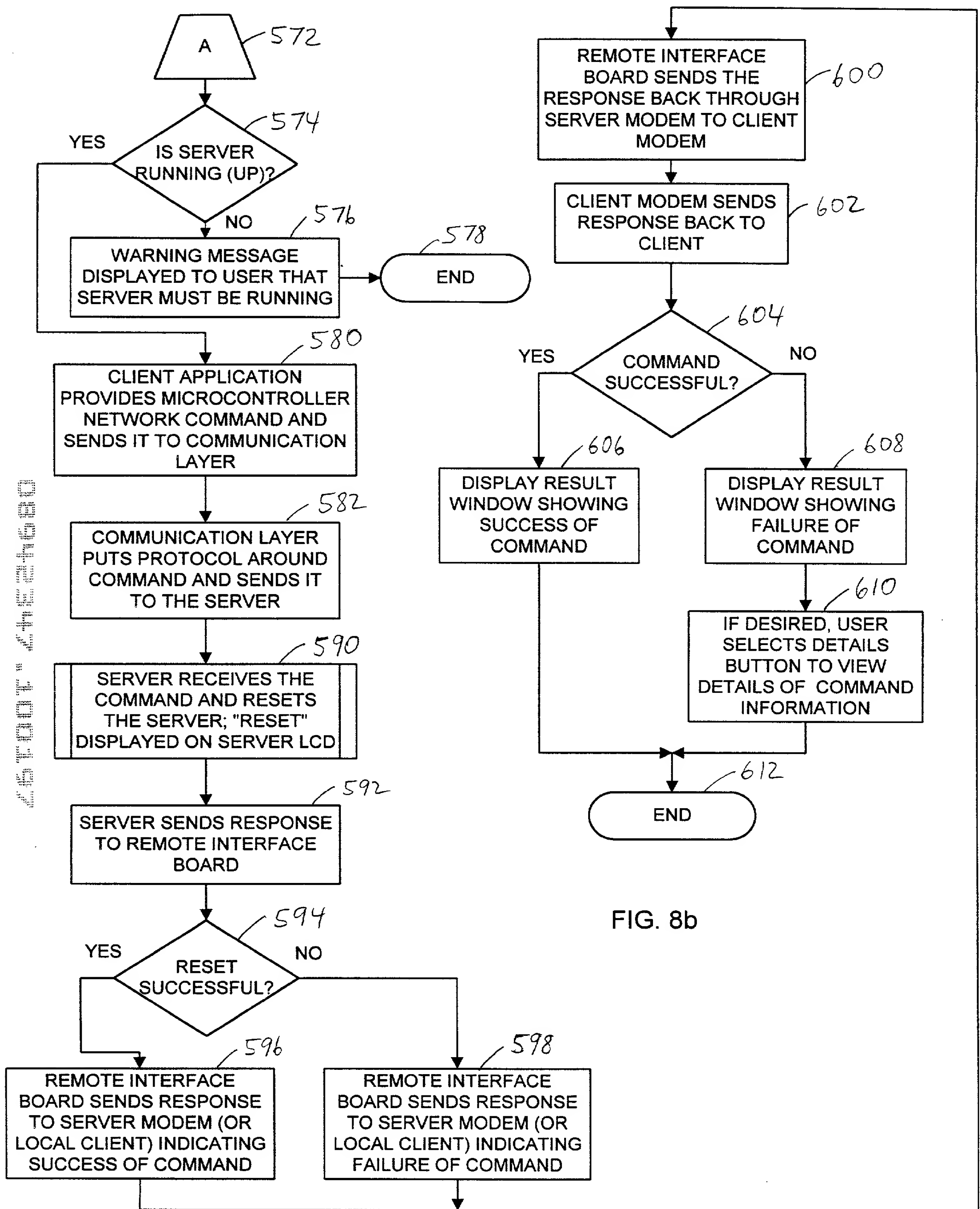
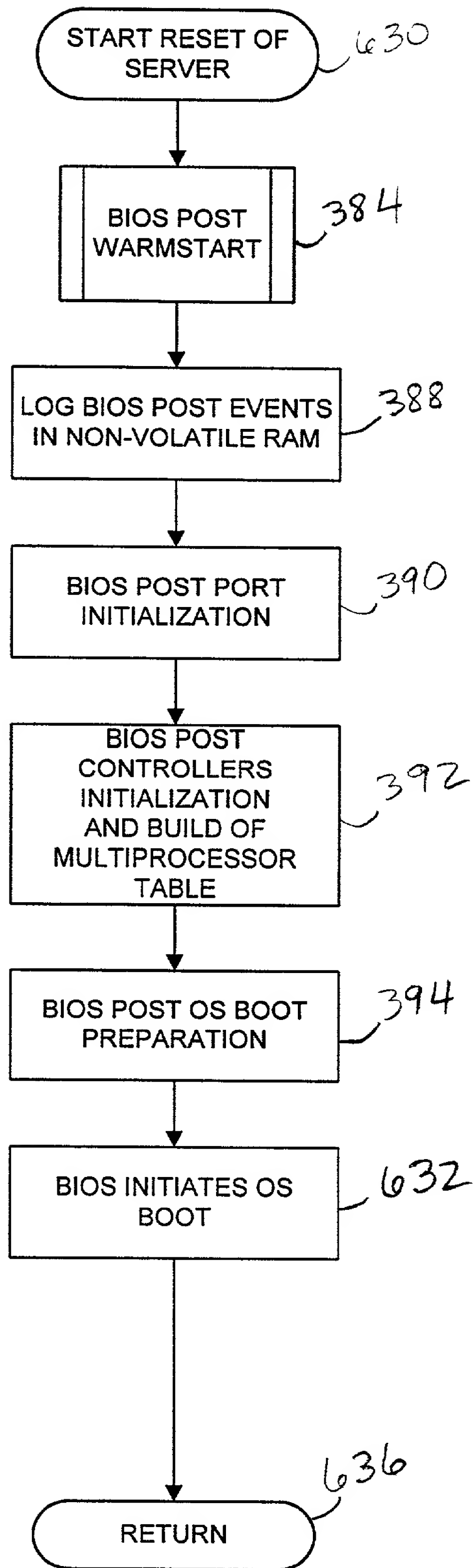


FIG. 8b



590



FIG. 9

DISPLAYING FLIGHT RECORDER PROCESS

670
↓

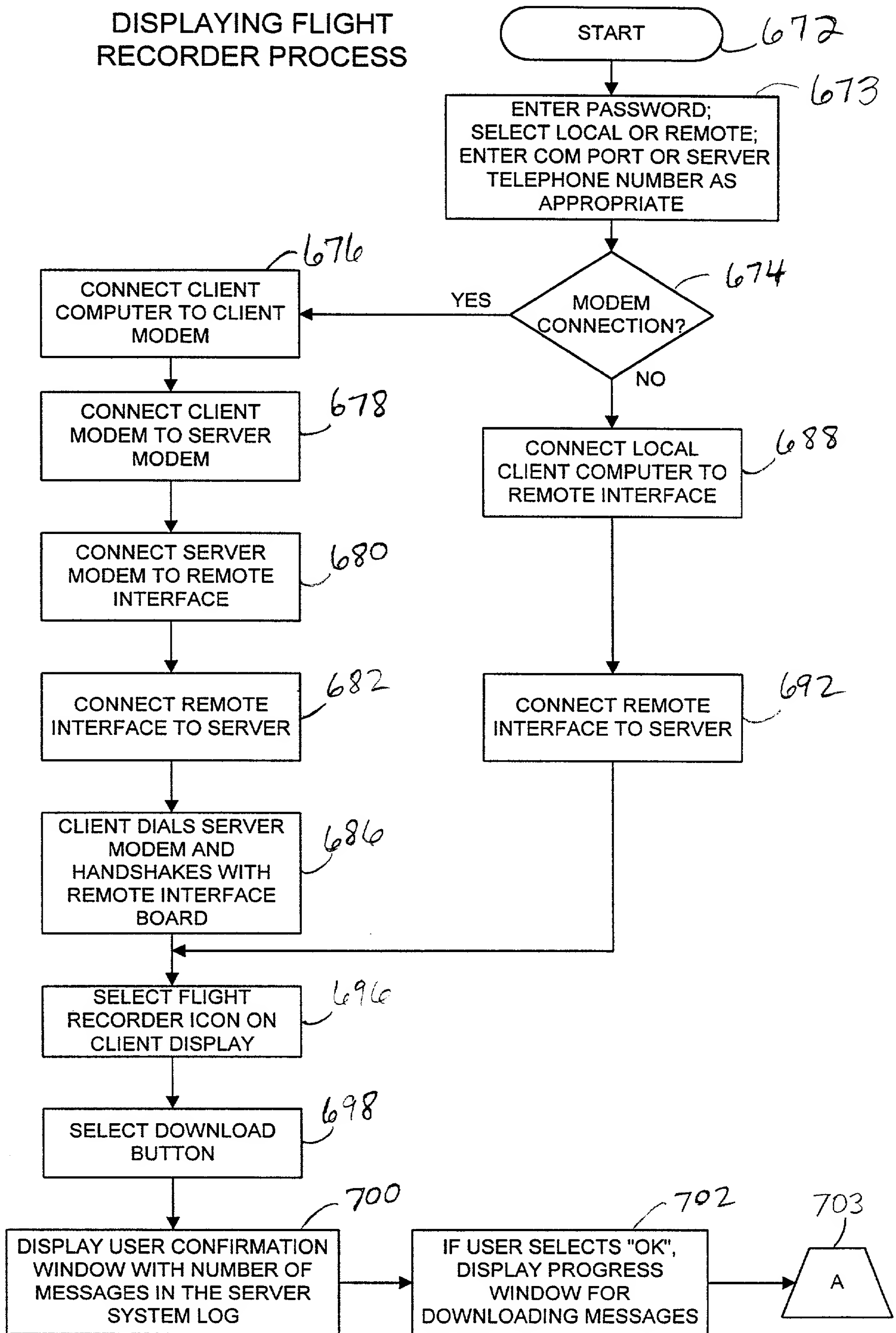


FIG. 10a

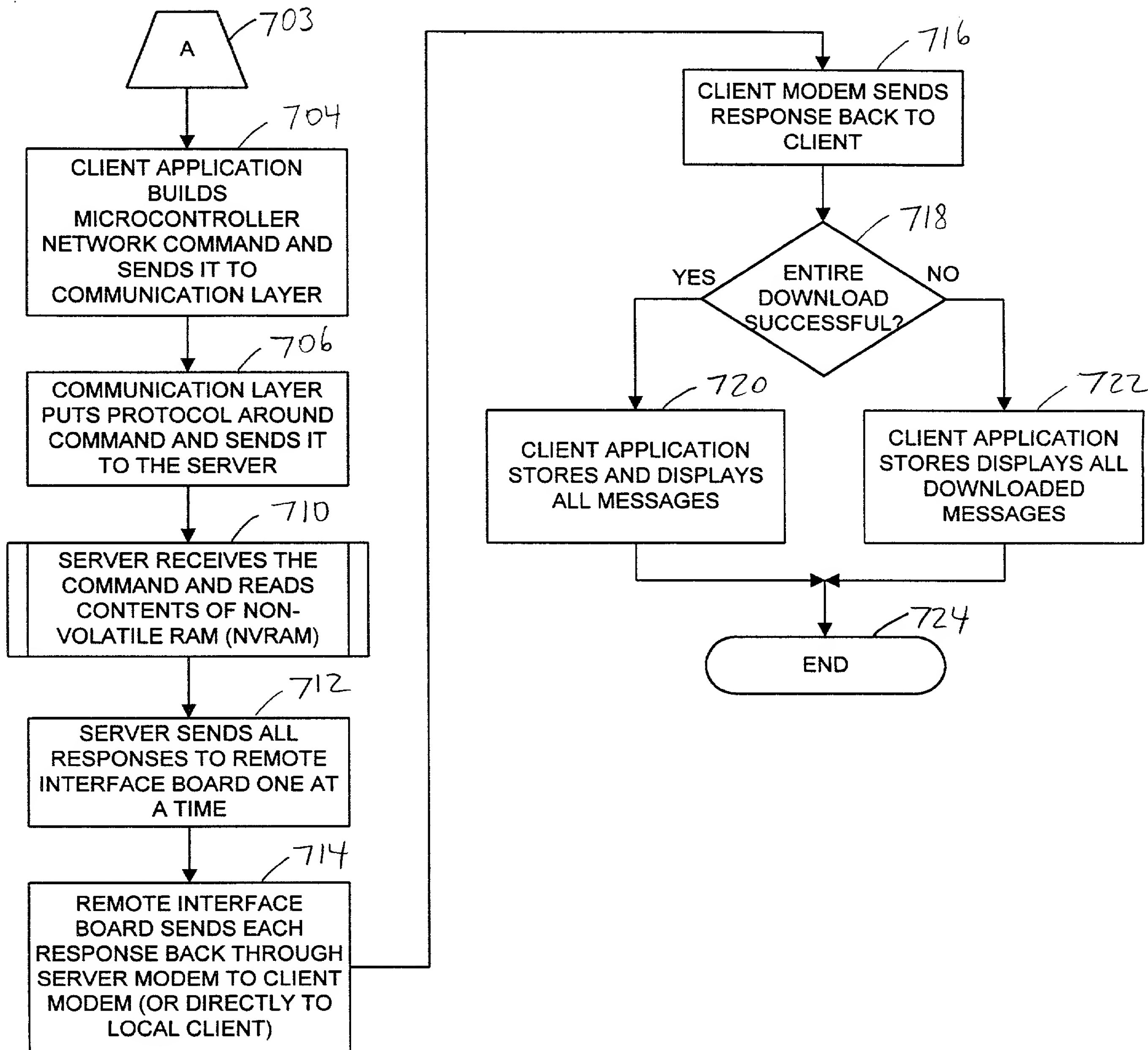


FIG. 10b

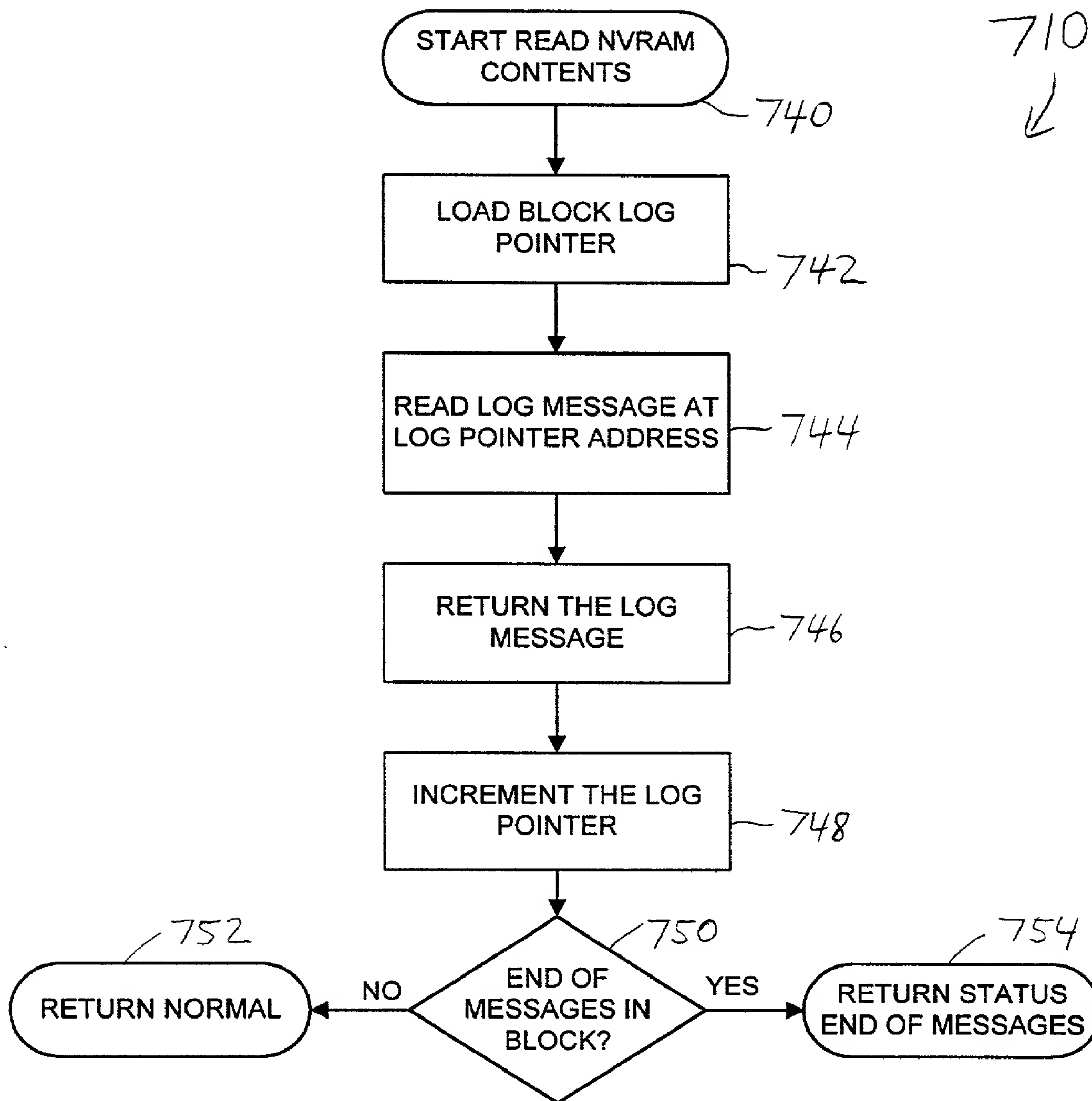
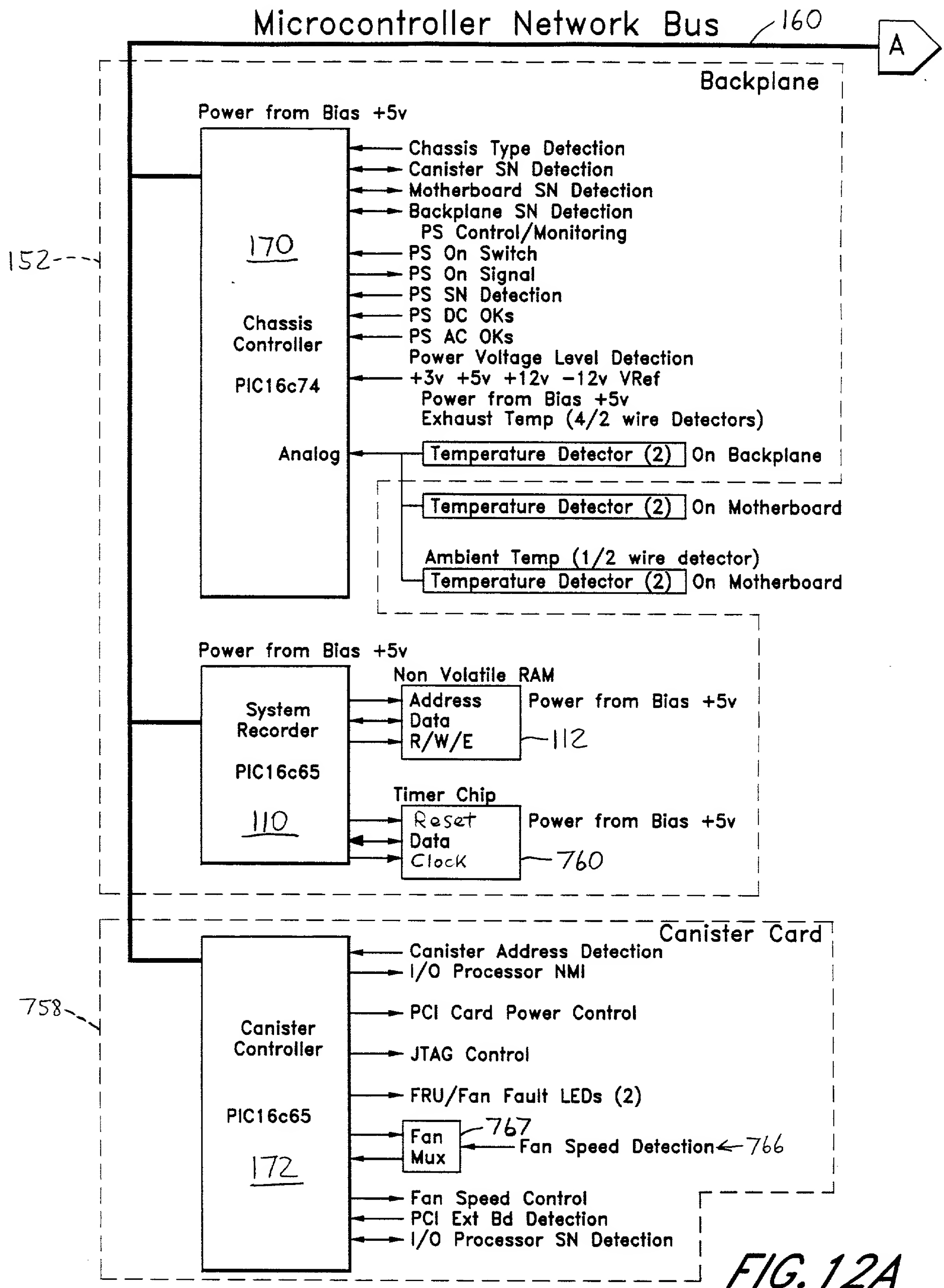


FIG. 11



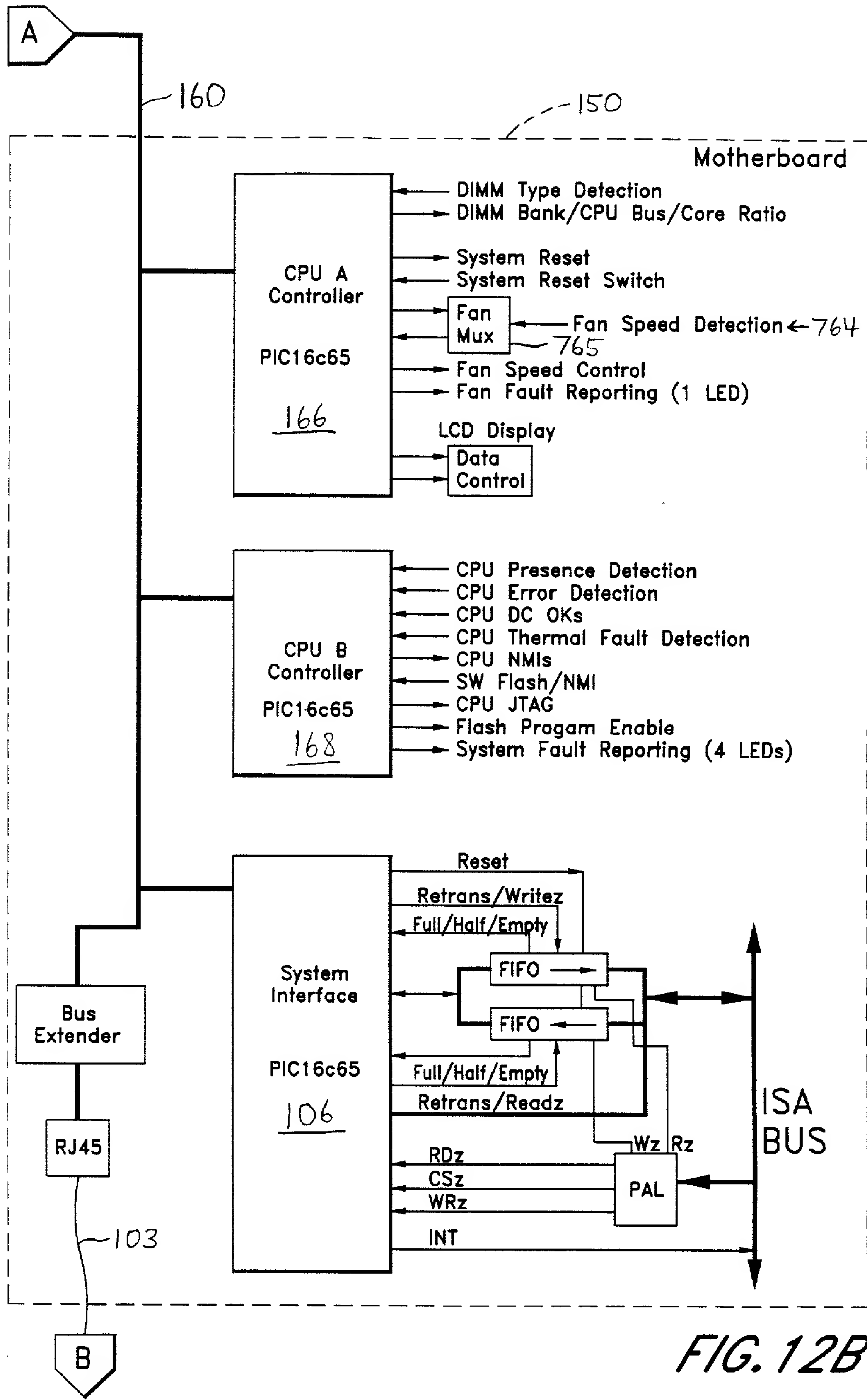


FIG. 12B

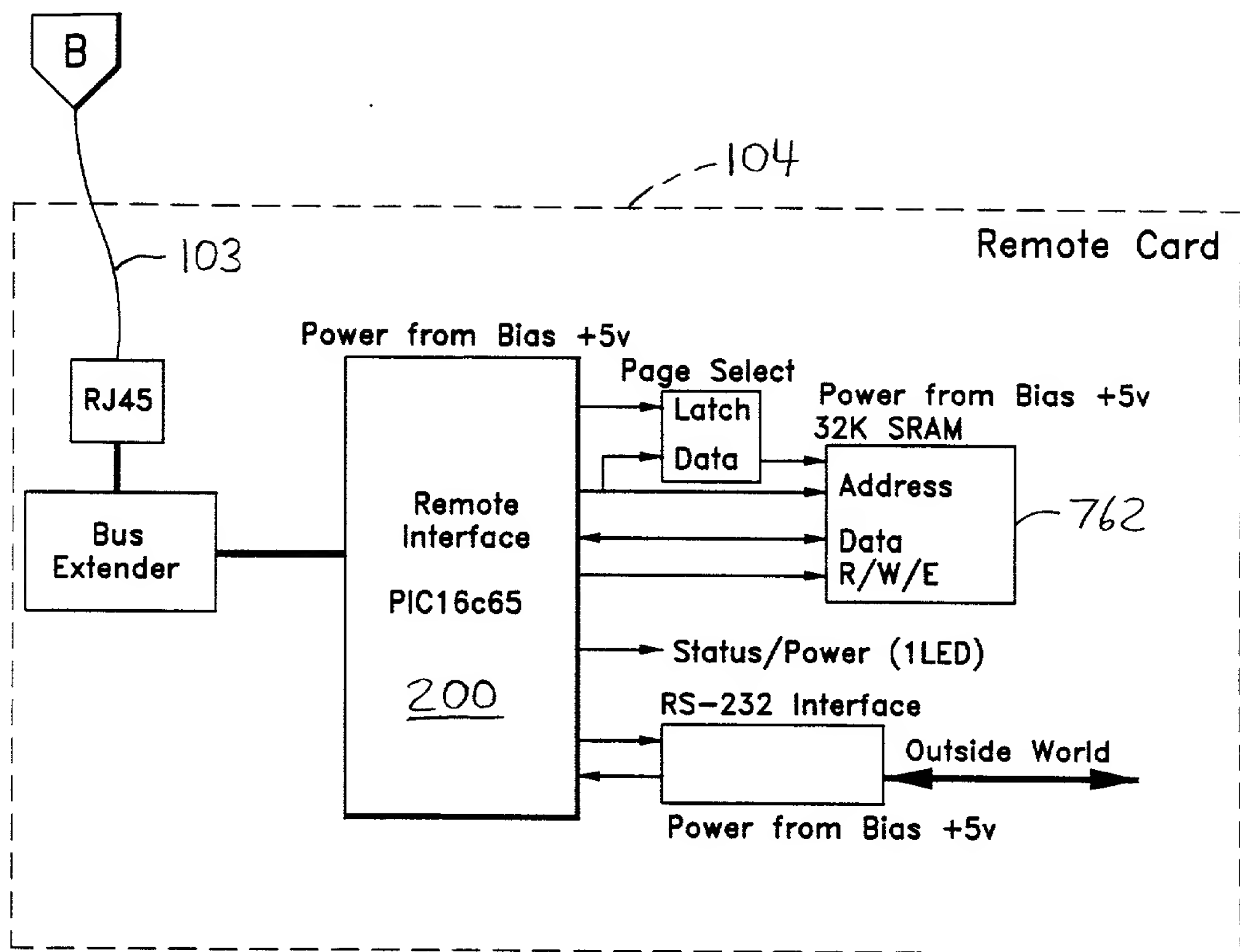


FIG. 12C

SYSTEM STATUS

770
↓

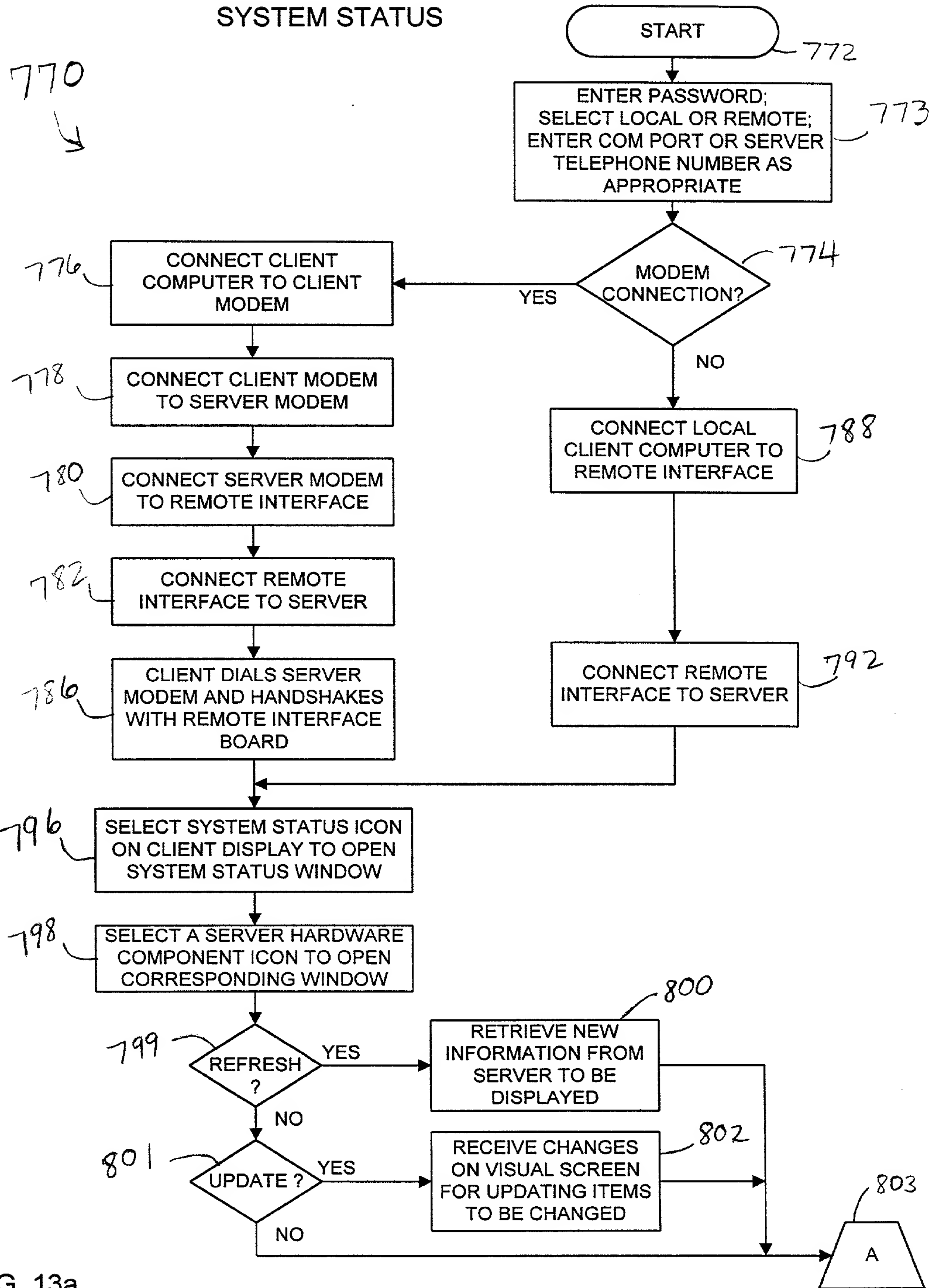


FIG. 13a

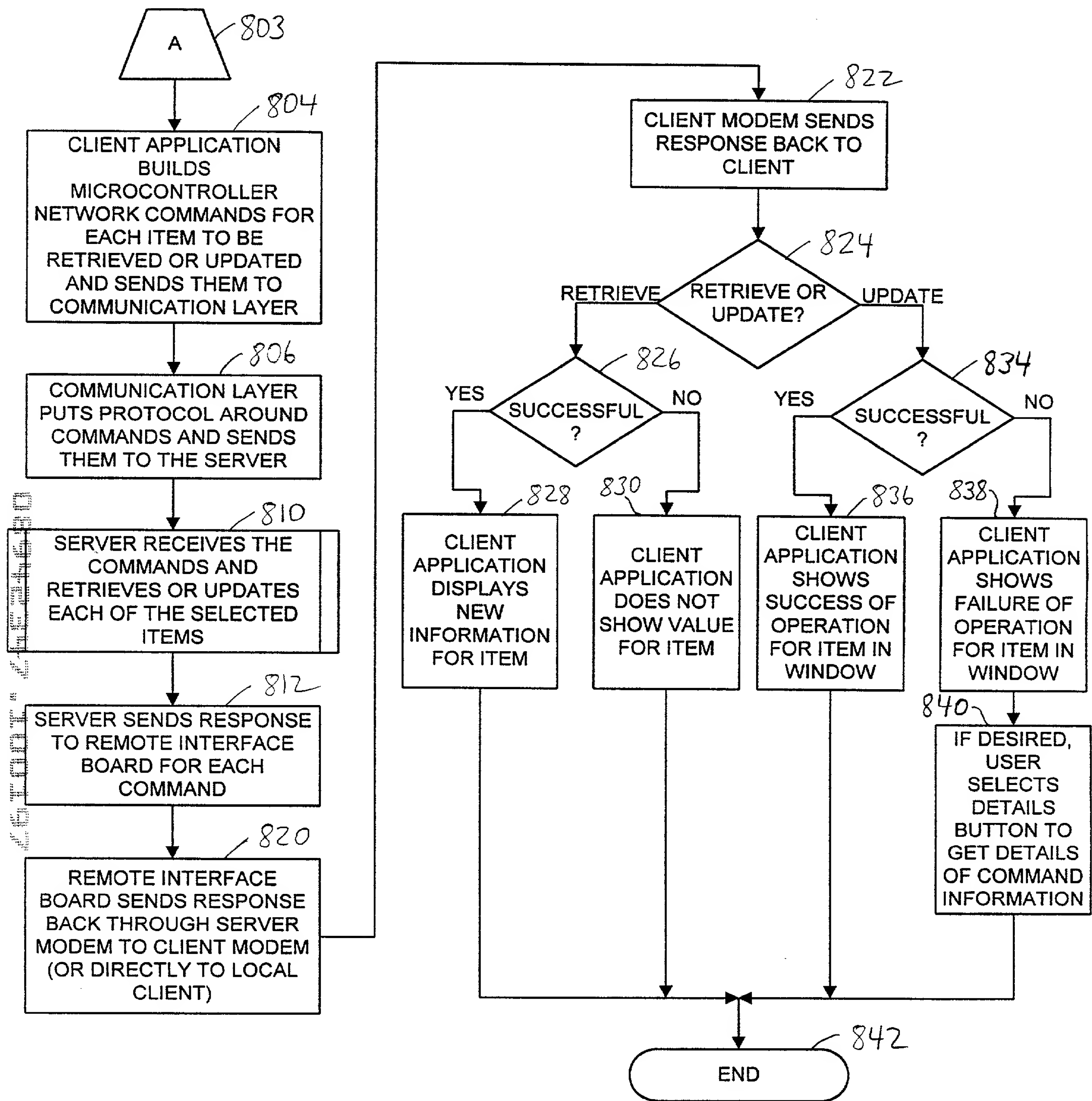


FIG. 13b

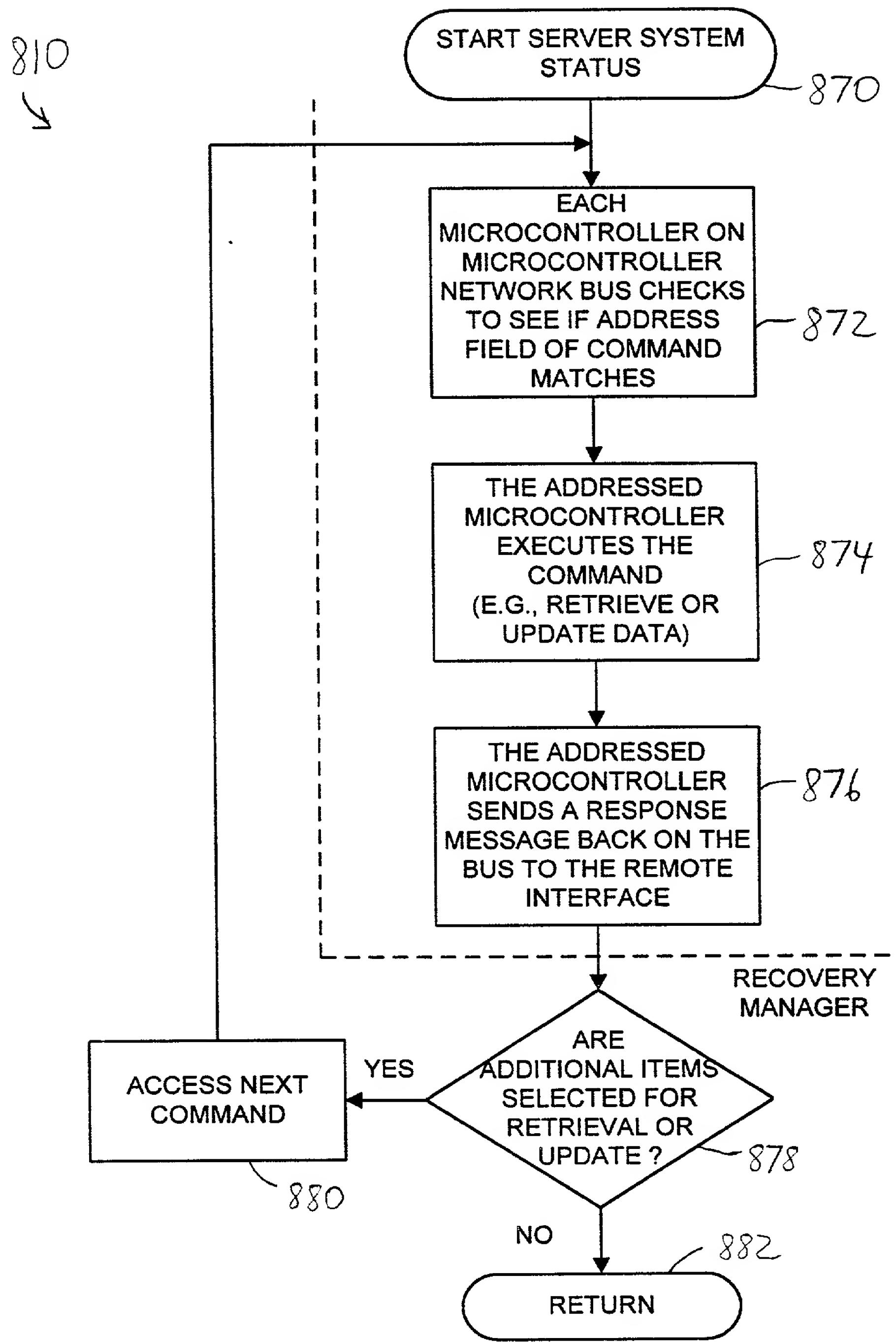


FIG. 14

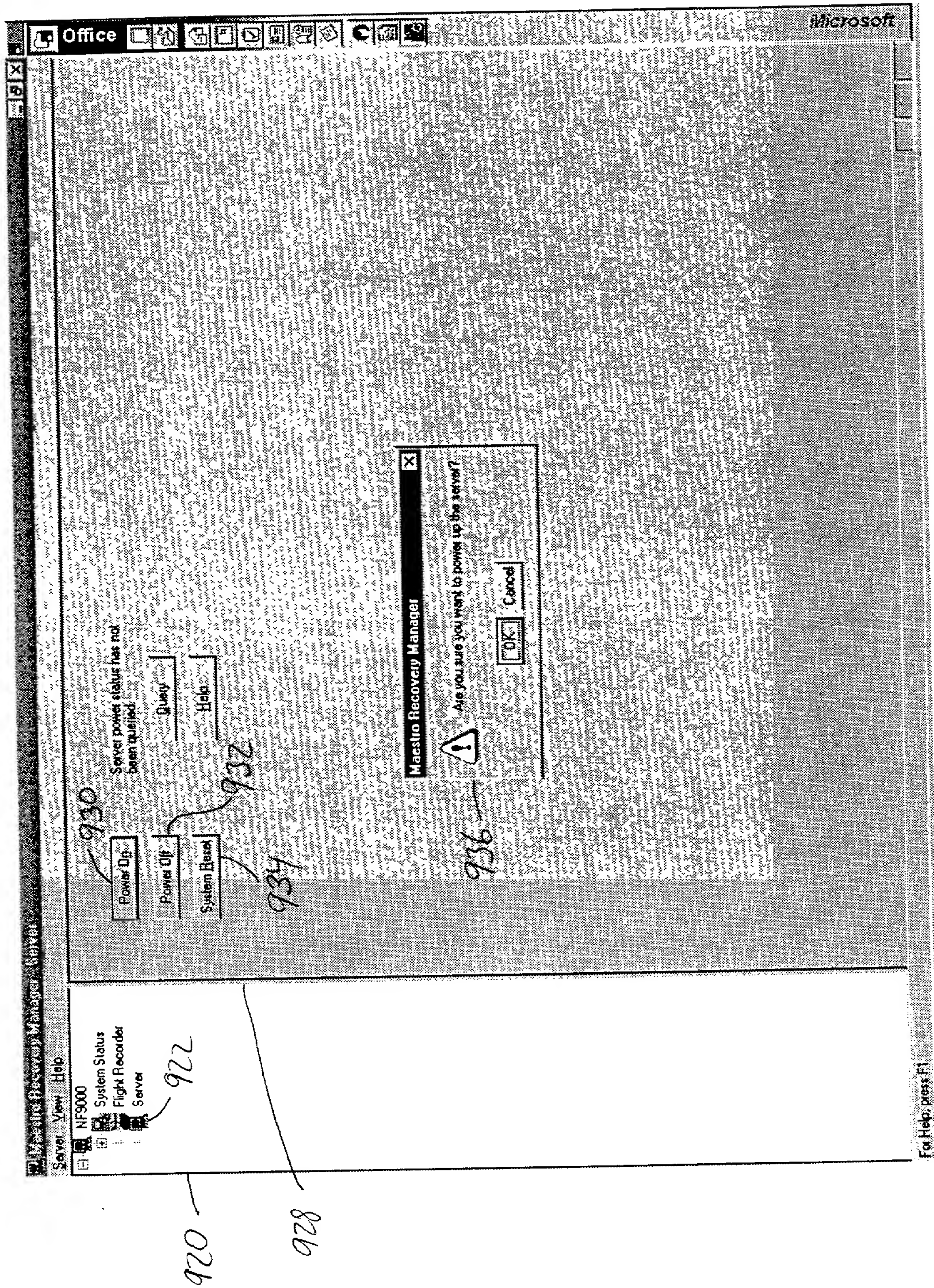


FIG. 15

946 948 950 952

Maestro Recovery Manager - Flight Recorder

Server View Help

NF9000

System Status

Flight Recorder

Server

Time Stamp	Severity	Message Source	Message
1997 Aug 29 04:10:45	Error	Wire Service Internal	0x9002
1997 Aug 29 04:10:44	Informational	Wire Service Internal	0x6010
1997 Aug 29 04:10:28	Warning	Wire Service Internal	0x6011
1997 Aug 29 04:07:05	Informational	BIOS	Verify Real Mode
1997 Aug 29 04:04:17	Informational	BIOS	Erase F2 key prompt

Download...

Save...

Print

Help

940

942

944

954

956

958

For Help, press F1

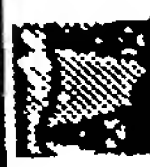
FIG. 16

Maestro Recovery Manager - System Status

Server View Help

NF9000

- System Status
- Power Supplies
- Temperatures
- Fans
- Processors
- I/O Controllers
- Serial Numbers
- Revisions
- Flight Recorder
- Server



Power Supplies



Temperatures



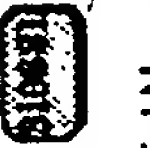
Fans



Processor



I/O Controllers



Serial Numbers



Revisions

970

972

974

976

978

980

982

984

960

962

Figure 17

985 986 987 988 989 990 991

Maestro Recovery Manager - Fans

Server View Help

- NF9000
 - System Status
 - Power Supplies
 - Temperatures
 - System Board
 - Canister A
 - Canister B
 - Canister C
 - Canister D
 - Processors
 - I/O Canisters
 - Serial Numbers
 - Revisions
 - Flight Recorder
 - Server

976
1000

Location	Fan	Speed	Speed Control	Fault Indicator LED	Fault	Low-speed fault threshold speed
System Board	1	4740	high	ON	YES	4740
	2	5160			YES	
	3	4260			YES	
	4	8520			YES	
	5	9540			no	
	6	480			no	
Canister A	1	4740	high	ON	no	4740
	2	5160			no	
Canister B	1	4740	high	ON	no	4740
	2	5160			no	
Canister C	1	4740	high	ON	no	4740
	2	5160			no	
Canister D	1	4740	high	ON	no	4740
	2	5160			no	

992

Refresh

Help

994

960

Figure 18

26 FOOT" 24E24580

Maestro Recovery Manager - Canister A

Server View Help

NF9000

- System Status
- Power Supplies
- Temperatures
- Fans
 - System Board
 - Canister A
 - Canister B
 - Canister C
 - Canister D
- Processors
- I/O Canisters
- Serial Numbers
- Revisions
- Flight Recorder
- Server

1008 17 Canister Present



Fan 1

Speed 4740

Fault? no



Fan 2

Speed 5160

Fault? no

Low speed fault
Threshold speed

4740

Speed Control

Low

High

Fault Indicator LED? ON

1004

1010

1006

1002

1012

1024

Refresh

Update

Help

Figure 19